

Slewing Drives



TransDrive was established to bring together our passion and experience in power transmission by being able to offer affordable, high-quality products to the power transmission and bearing market. Built on the philosophy of improving performance and quality of all of our TransDrive products.

Transdrive products have been manufactured and tested to meet ISO standards and the tough, working conditions of heavy industries.

Our team have experience in power transmission and bearings. Every product we design and manufacture is backed by years of industry knowledge and an understanding of what our customers and the market need.

At TransDrive, our goal is simple: to provide accessible, high-quality products at affordable pricing. With an unwavering commitment to excellence, TransDrive operates with a focus on providing innovative industry solutions.

Whether it is through our custom products, the standard range of pulleys, slew drives, chains and sprockets, TransDrive is dedicated to delivering effective solutions for the trades that offer increased productivity and reliability.

TransDrive exclusively supply to Resellers, Wholesalers and Original Equipment Manufacturers (OEMs) only.

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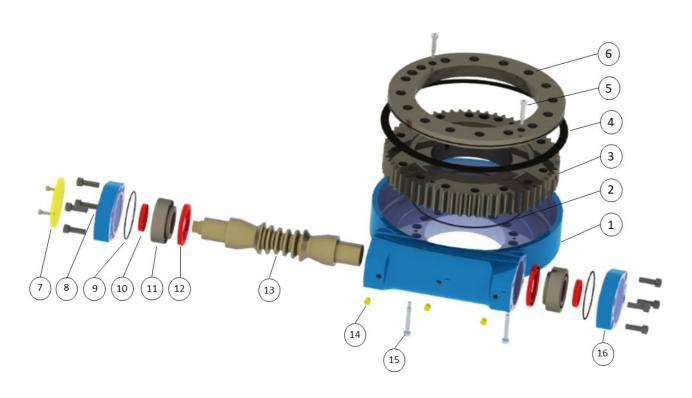
Get in touch:

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Components of a Slewing Drive



- 1. Enclosed Housing
- 2. Large O-ring
- 3. Slewing Ring
- 4. Top plate seal
- 5. Upper positioning bolts
- 6. Top plate
- 7. Non-drive end cover
- 8. End cap and bolts

- 9. End cap O-rings
- 10. Outer oil seals
- 11. Taper roller bearing
- 12. Inner oil seals
- 13. Worm shaft
- 14. Grease nipples
- 16. Drive end adaptor cap
- 15. Lower positioning bolts

Horizontal Installation

It is advised to mount the slewing drives upside down on the azimuth axis in solar applications for better protection and add protection for the elevation axis. For other applications, the mounting directions shall be based on the evaluation of the protection level and it shall be better for better protection.

Vertical Installation

It is advised to mount the slewing drives referring to attached drawing upside in solar applications for better protection. For other applications, the mounting directions shall be based on the evaluation of the protection level and it shall be better for better protection.

Transport, Storage & Mounting Preparation

To ensure slewing drives last as long as possible and perform optimally, follow these guidelines:

- Always transport and store slewing drives horizontally to prevent damage.
- Avoid shock loads to protect the raceways from harm.
- ▶ Be careful not to dislodge seals or grease fittings when moving the drives.

In humid conditions, light to mild surface corrosion might occur, but it can be easily removed from the external surfaces. It's crucial to keep the raceways well-greased to prevent rust. TransDrive slewing drives are coated with epoxy in RAL 5005 Blue for added protection.

When stacking unwrapped bearings vertically, use wooden or rubber spacers to avoid surface damage. Protect exposed gear teeth from impact damage.

Do not suspend slewing rings from a crane with a single sling, and avoid placing them on the ground vertically, as they may deform under their own weight.

Flatness Defects

Under load, flatness defects must remain within the specified limits to prevent tight spots or seizure, both of which can reduce the ring's operating life. The listed values pertain to "long wave deviations" around the circumference. It's important to note that X-roller bearings require finer tolerances than ball bearings for smooth operation.

Shorter wave defects (e.g., between two bolt holes) must not exceed 25% of this value.

Radial direction defects, known as "conicity," must not exceed 0.05 mm/m based on the raceway diameter.

Raceway	7	9	12	14	17	19	21	25
Flatness deviation in	0.04"	0.12"	0.15"	0.15"	0.15"	0.17"	0.20"	0.20"

Tracking Accuracy

Under load, flatness defects must remain within the specified limits to prevent tight spots or seizure, both of which can reduce the ring's operating life. The listed values pertain to "long wave deviations" around the circumference. It's important to note that X-roller bearings require finer tolerances than ball bearings for smooth operation.

Shorter wave defects (e.g., between two bolt holes) must not exceed 25% of this value.

Radial direction defects, known as "conicity," must not exceed 0.05 mm/m based on the raceway diameter.



Lubrication

TransDrive slewing drives are factory filled with a satisfactory grease. The re-greasing period is best determined by the environment in which the drive itself is kept. During re-greasing it is best to rotate the bearing to ensure the lubricant is evenly lubricated.

Environment	Recommended period
Dry, clean workshop	1000hrs duty or 12 months
Outside, exposed	500hrs duty or 6 months
Aggressive	50hrs duty or 2 months
Extreme	Continuous

The amount of grease required is given in the following table:

Raceway	3	5	7	9	12	14	17	19	21	25
Raceway	-	15	20	35	50	60	75	105	130	150
Worm Gear	35	60	65	100	110	110	120	130	140	150
Worm support brgs	7	7	7	10	10	10	10	10	10	10

Measurements are in grains

The responsibilty remains with the client to ensure the bearing is sufficiently and freshly lubricated at time of installation. Below are some brands and their greases that are highly recommended.

Brand	Grease	Operating temp range
Kluber	Isoflex NBU 15	-20 to +120 C
Mobil	Mobiltemp SHC 100	-20 to +120 C
Cougar	CG 8100	-40 to +200 C

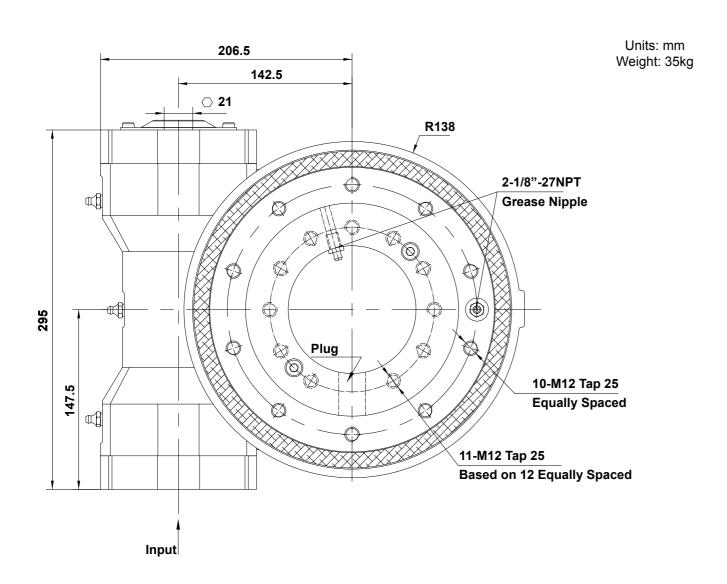
FWA Series

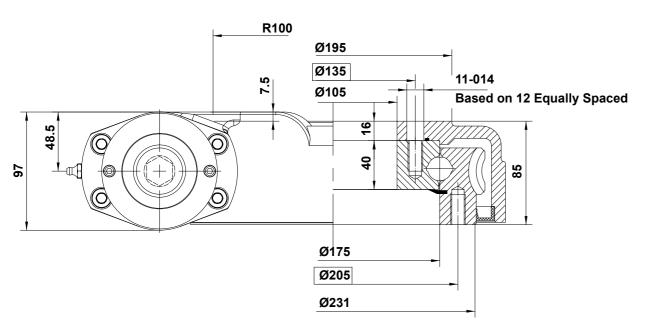
The FWA Series slewing drives are robust, sealed, and high-precision rotary actuators, ideal for demanding outdoor and industrial applications. Their advanced design offers enhanced strength, environmental protection, and reliability over traditional slewing drives

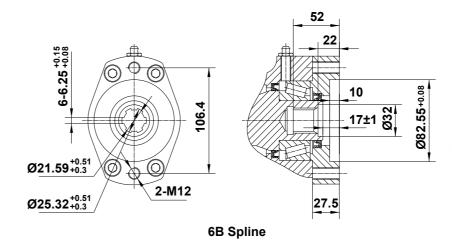
Our range

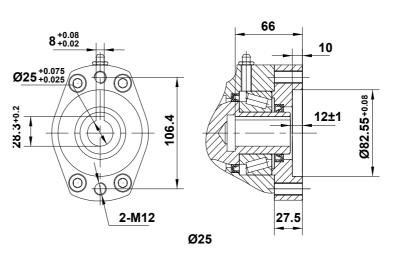
- ► FWA7
- ► FWA9
- ► FWA12
- ► FWA14
- ► FWA14-2
- ► FWA17
- ► FWA17-2
- ► FWA19
- ► FWA21
- ► FWA21-2
- ► FWA25
- ► FWA25-2









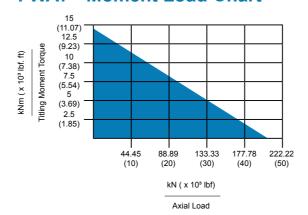




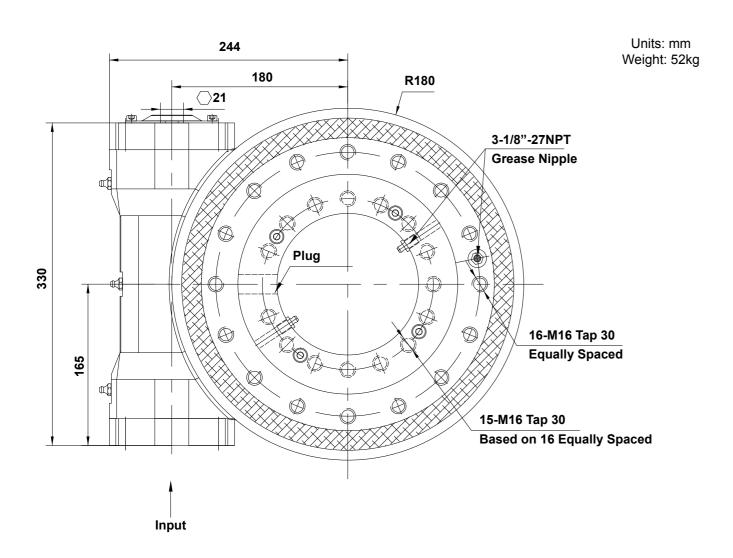
FWA7 - Slewing Drive Performance Parameters

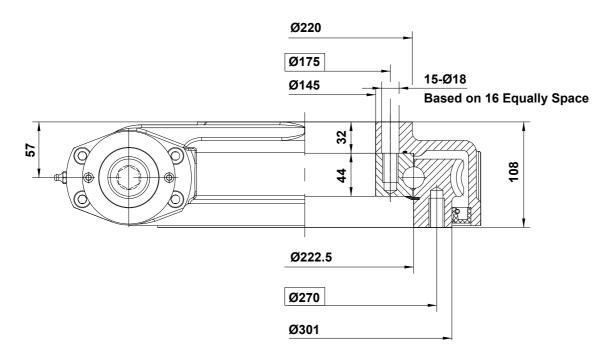
Model	Output Torque	Tilting Moment Torque	Holding Torque	Axial Load	Radial Load	Ratio	Backlash	Weight
FWA7	3.5kNm	14.7kNm	20.6kNm	227kN	92.7kN	47:1	≤0.15°	35kg
FVVA/	2583lbf.ft	10.8 x 10 ³ lbf.ft	15.2 x 10³lbf	51 x 10 ³ lbf	20.8 x 10 ³ lbf			

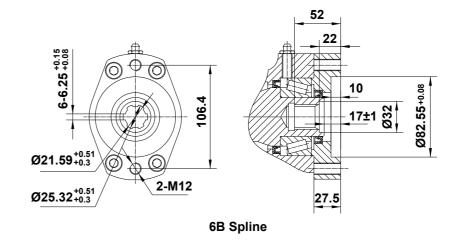
FWA7 - Moment Load Chart

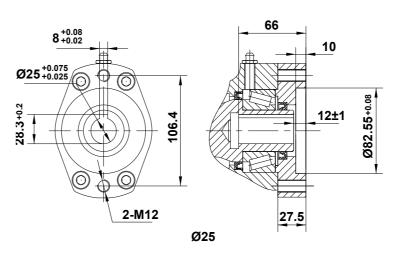


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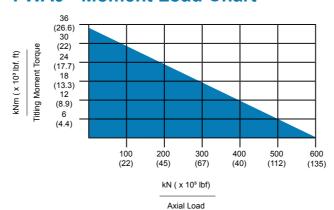


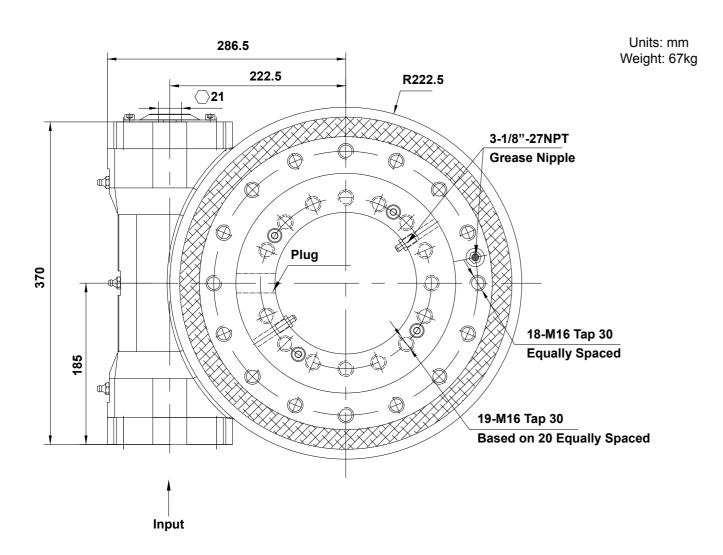


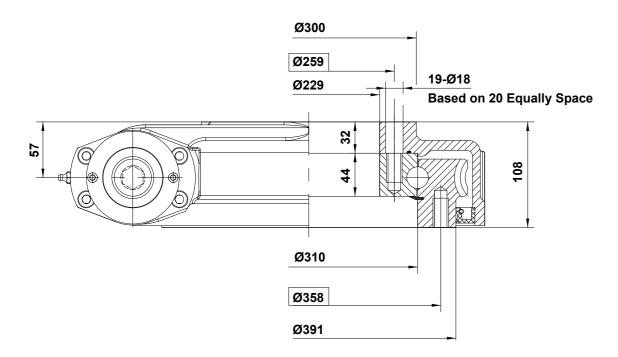
FWA9 - Slewing Drive Performance Parameters

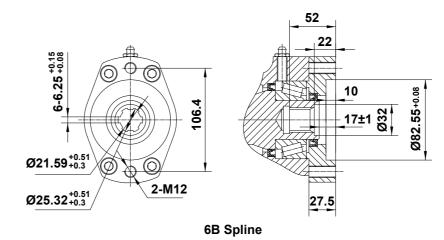
Model	Output Torque	Tilting Moment Torque	Holding Torque	Axial Load	Radial Load	Ratio	Backlash	Weight
FWA9	8kNm	35.6kNm	39.8kNm	550kN	220kN	62:1	≤0.15°	52kg
FWA9	5904lbf.ft	26.3 x 10 ³ lbf.ft	29.37 x 10 ³ lbf	130.3 x 10 ³ lbf	49.4 x 10 ³ lbf	62.1		

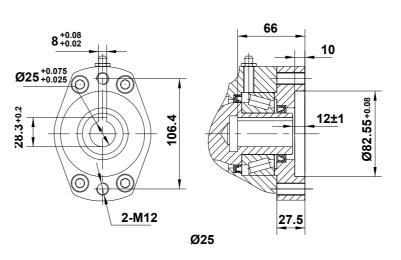
FWA9 - Moment Load Chart









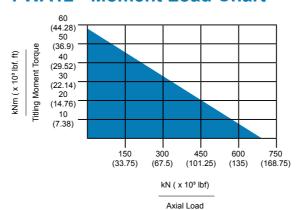




FWA12 - Slewing Drive Performance Parameters

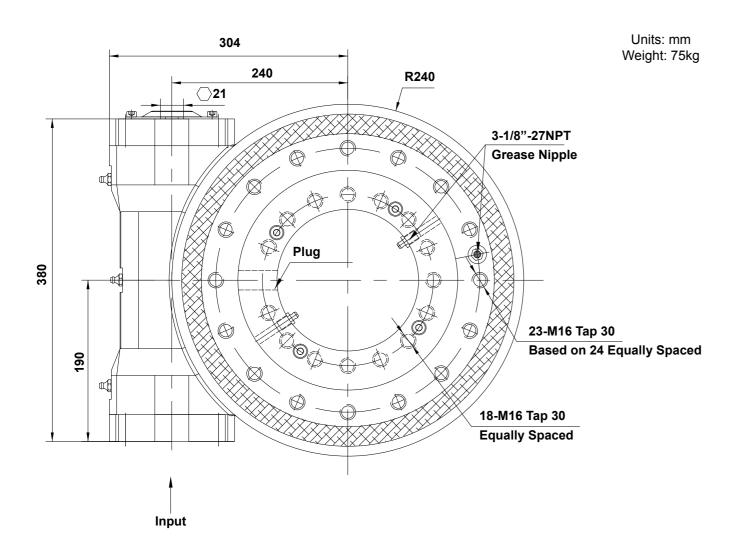
Model	Output Torque	Tilting Moment Torque	Holding Torque	Axial Load	Radial Load	Ratio	Backlash	Weight
FWA12	9.5kNm	57kNm	44.3kNm	760kN	280kN	79:1	≤0.15°	67kg
FWAIZ	7011lbf.ft	41.2 x 10 ³ lbf.ft	32.7 x 10 ³ lbf	171.1 x 10 ³ lbf	62.9 x 10 ³ lbf			

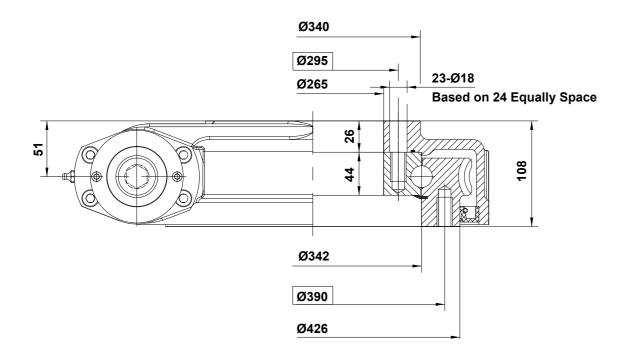
FWA12 - Moment Load Chart



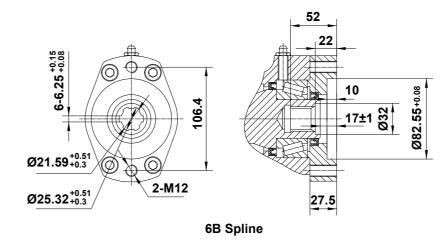
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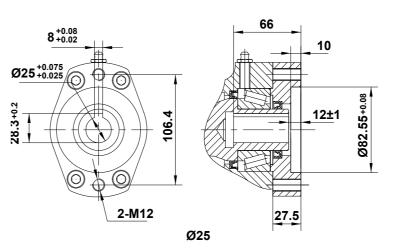
FWA14

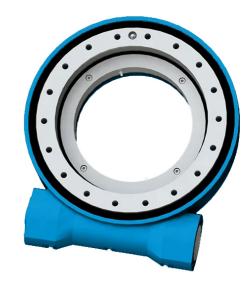




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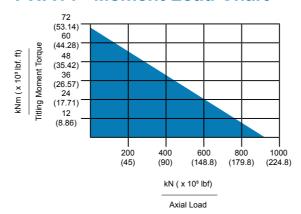




FWA14 - Slewing Drive Performance Parameters

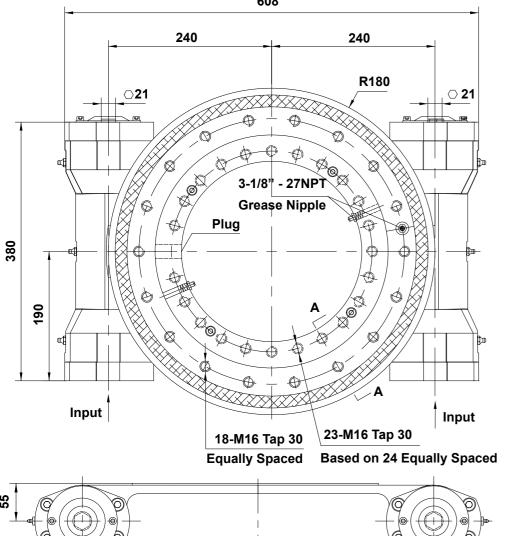
Model	Output Torque	Tilting Moment Torque	Holding Torque	Axial Load	Radial Load	Ratio	Backlash	Weight
FWA14	10.8kNm	71.2kNm	49.5kNm	960kN	360kN	86:1	≤0.15°	75kg
FVVA14	7970lbf.ft	52.5 x 10 ³ lbf.ft	36.5 x 10 ³ lbf	215.8 x 10 ³ lbf	80.9 x 10 ³ lbf			

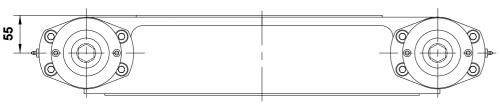
FWA14 - Moment Load Chart

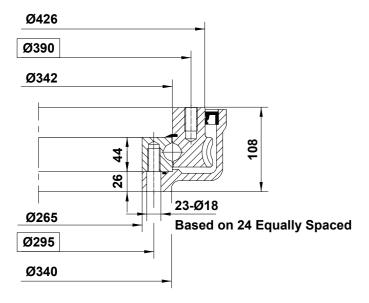


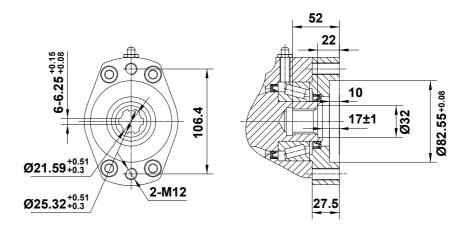
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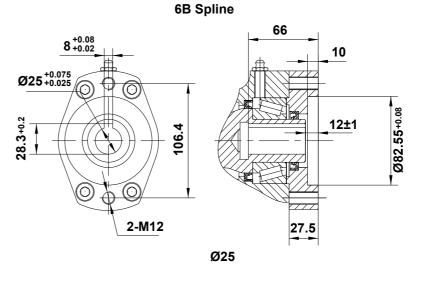










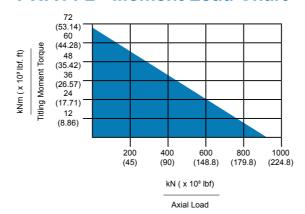


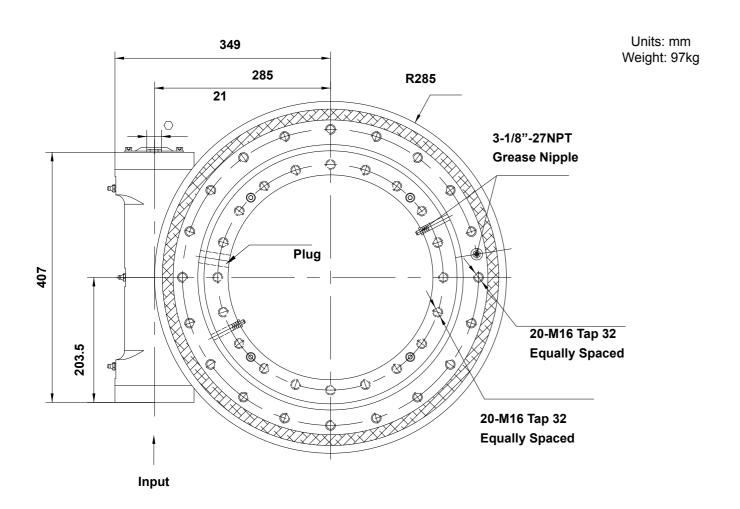


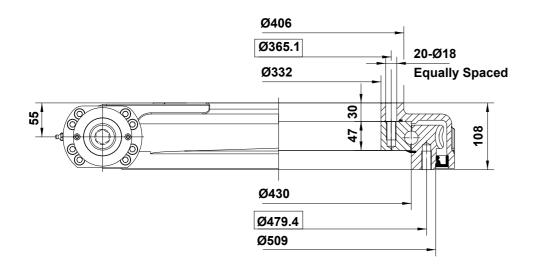
FWA14-2 - Slewing Drive Performance Parameters

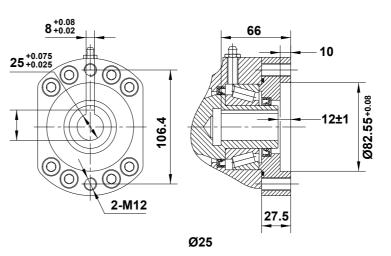
Model	Output Torque	Tilting Moment Torque	Holding Torque	Axial Load	Radial Load	Ratio	Backlash	Weight
FWA14-2	16.2kNm	71.2kNm	74kNm	956kN	363kN	86:1	≤0.17°	0014
FVVA 14-2	11956lbf.ft	62.6 x 10 ³ lbf.ft	54.6 x 10 ³ lbf	216.9 x 10 ³ lbf	81.6 x 10 ³ lbf			90kg

FWA14-2 - Moment Load Chart







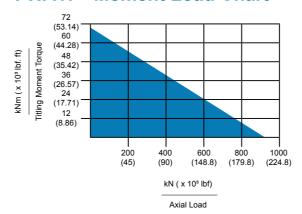


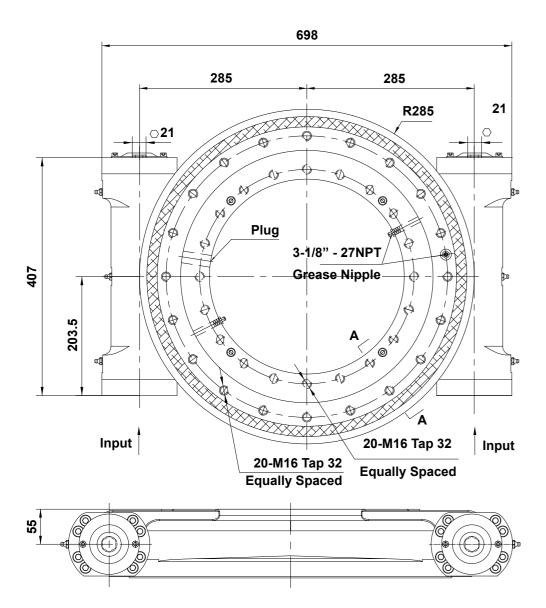


FWA17 - Slewing Drive Performance Parameters

Model	Output Torque	Tilting Moment Torque	Holding Torque	Axial Load	Radial Load	Ratio	Backlash	Weight
FWA17	12.96kNm	142.4kNm	74kNm	1166kN	435kN	104:1	≤0.1°	97kg
FWAI7	9564lbf.ft	105 x 10 ³ lbf.ft	54.6 x 10 ³ lbf	262 x 10 ³ lbf	97.8 x 10 ³ lbf			

FWA17 - Moment Load Chart



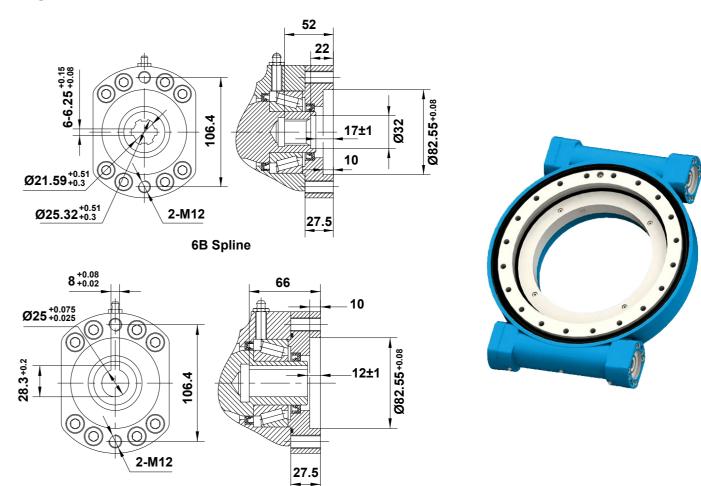


Units: mm Weight: 115kg

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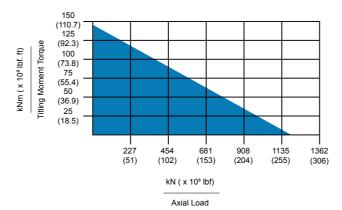


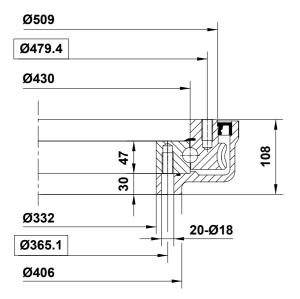
FWA17-2 - Slewing Drive Performance Parameters

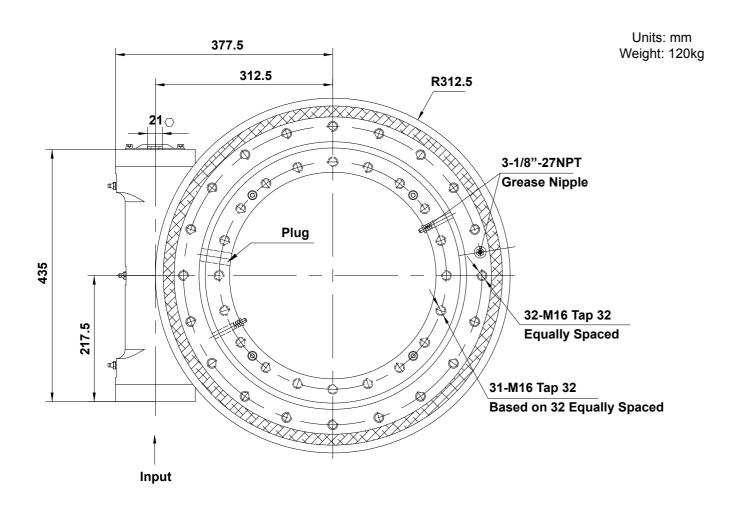
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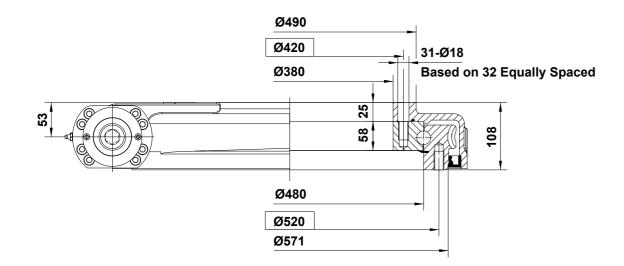
Model	Output Torque	Tilting Moment Torque	Holding Torque	Axial Load	Radial Load	Ratio	Backlash	Weight
FWA17-2	19.44kNm	142.4kNm	110kNm	1166kN	435kN	104:1	≤0.15°	115kg
FWAI7-2	14347lbf.ft	105 x 10 ³ lbf.ft	81.2 x 10 ³ lbf	262 x 10 ³ lbf	97.8 x 10 ³ lbf			

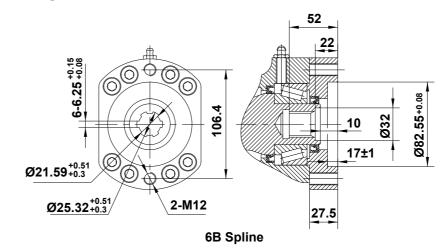
FWA17-2 - Moment Load Chart

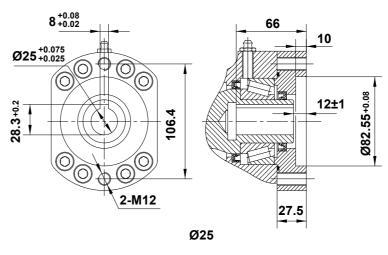


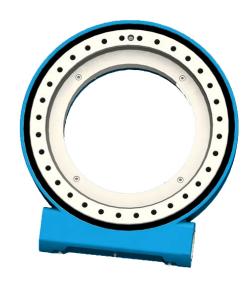








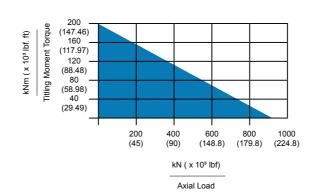




FWA19 - Slewing Drive Performance Parameters

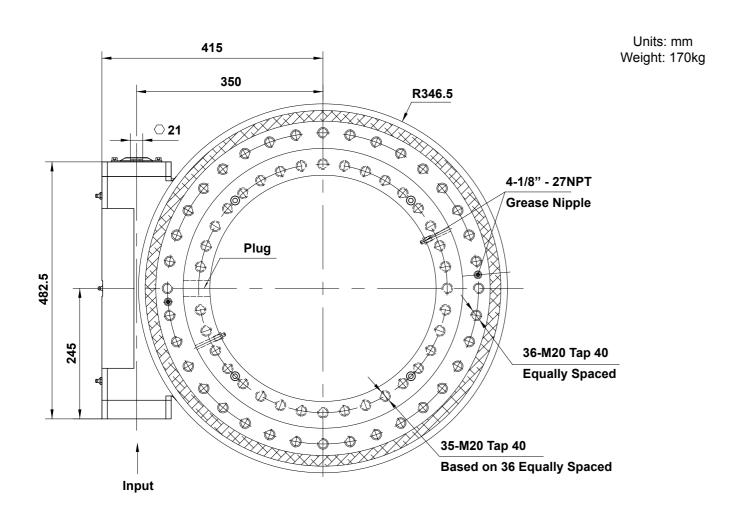
Model	Output Torque	Tilting Moment Torque	Holding Torque	Axial Load	Radial Load	Ratio	Backlash	Weight
FWA19	18.5kNm	196kNm	82kNm	1810kN	675kN	94:1	≤0.1°	1201-
FWAI9	13640lbf.ft	144.5 x 10 ³ lbf.ft	60.5 x 10 ³ lbf	406 x 10 ³ lbf	151.7 x 10 ³ lbf	94.1	≥0.1	120kg

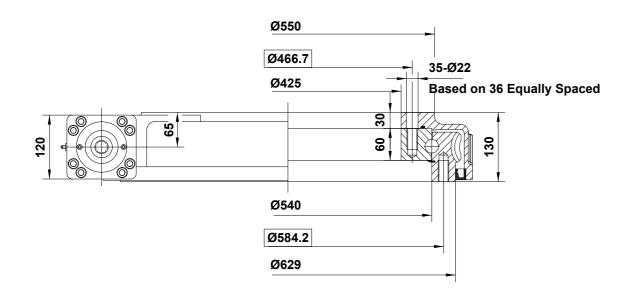
FWA19 - Moment Load Chart



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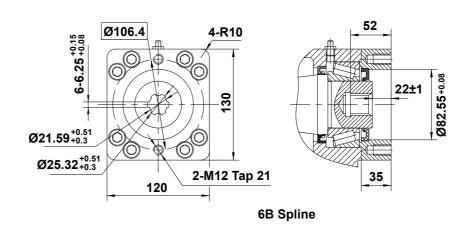


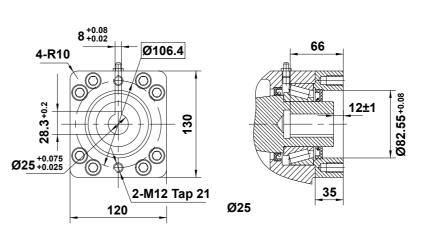


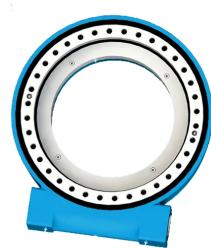
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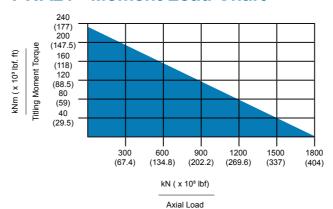


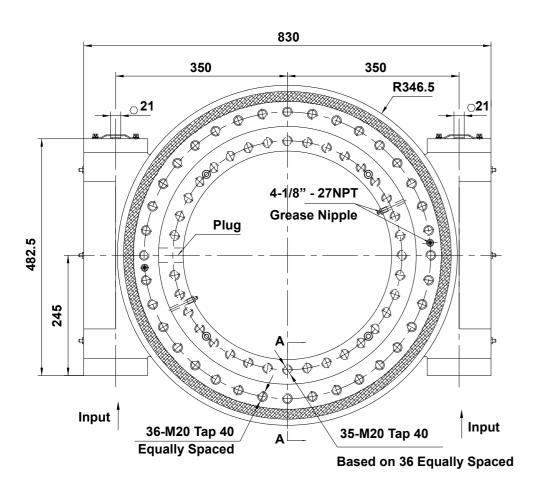


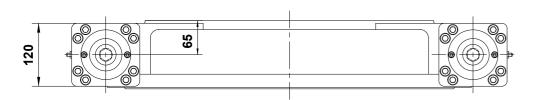
FWA21 - Slewing Drive Performance Parameters

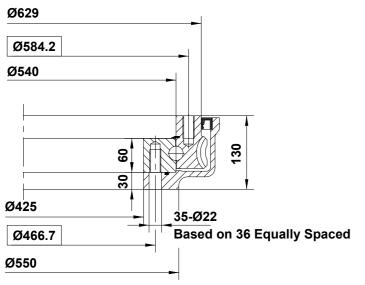
Model	Output Torque	Tilting Moment Torque	Holding Torque	Axial Load	Radial Load	Ratio	Backlash	Weight
FWA21	28.7kNm	203kNm	107kNm	1600kN	650kN	90:1	≤0.1°	1701
FWAZI	21180lbf.ft	150 x 10 ³ lbf.ft	78.9 x 10 ³ lbf	359.7 x 10 ³ lbf	146 x 10 ³ lbf	90.1	≥0.1	170kg

FWA21 - Moment Load Chart



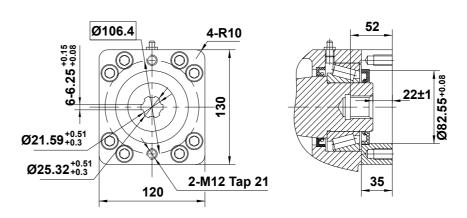




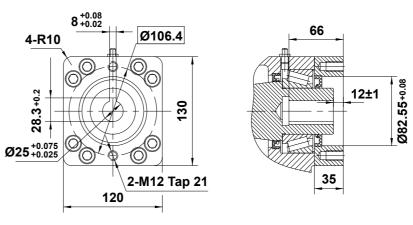


Units: mm Weight: 200kg

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6B Spline



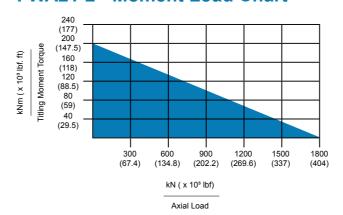


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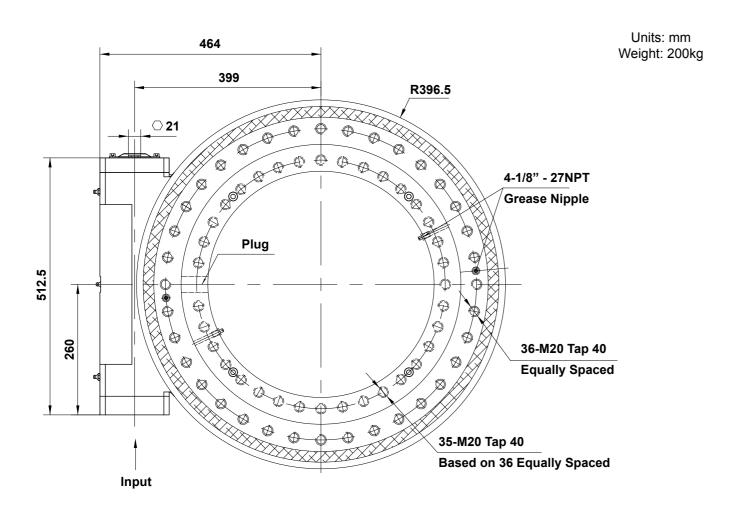
FWA21-2 - Slewing Drive Performance Parameters

Model	Output Torque	Tilting Moment Torque	Holding Torque	Axial Load	Radial Load	Ratio	Backlash	Weight
FWA21-2	48kNm	203kNm	181kNm	1600kN	650kN	90:1	≤0.13°	2001
FVVAZ 1-Z	35400lbf.ft	150 x 10 ³ lbf.ft	141 x 10³lbf	359.7 x 10 ³ lbf	146 x 10 ³ lbf	90.1	≥0.13	200kg

FWA21-2 - Moment Load Chart







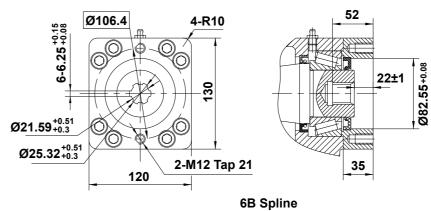
Ø650 Ø565 35-Ø22 Ø525 Based on 36 Equally Spaced 130 Ø630 Ø675 Ø726

Every effort has been taken to ensure that the data listed in this catalogue is correct.

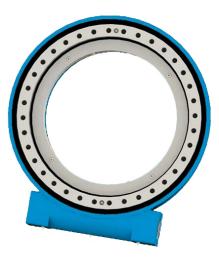
TransDrive will not accept liability for any damage or loss caused as a result of the data in this catalogue.

INPUT

4-R10







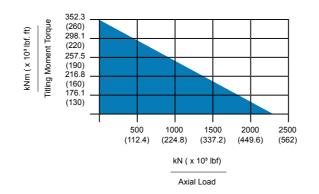
12±1 Ø25 +0.075 2-M12 Tap 21 Ø25 120

Ø106.4

FWA25 - Slewing Drive Performance Parameters

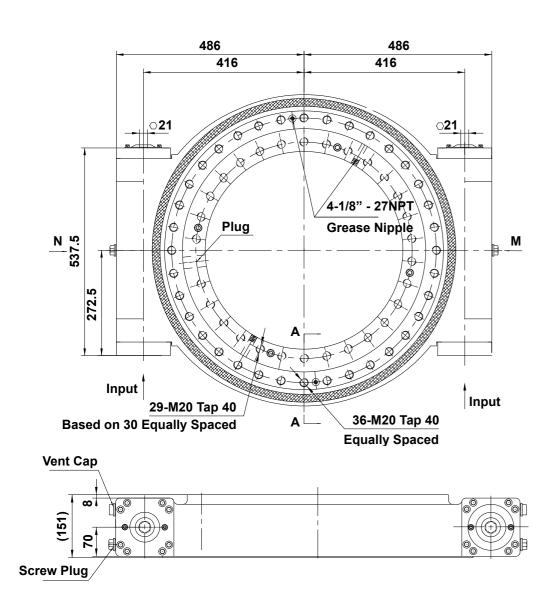
Model	Output Torque	Tilting Moment Torque	Holding Torque	Axial Load	Radial Load	Ratio	Backlash	Weight
FWA25	34.2kNm	310kNm	160kNm	2400kN	950kN	104:1	≤0.1°	200ka
FVVA25	25240lbf.ft	229 x 10 ³ lbf.ft	118 x 10 ³ lbf	539.5 x 10 ³ lbf	213.6 x 10 ³ lbf	104.1	≥0.1	200kg

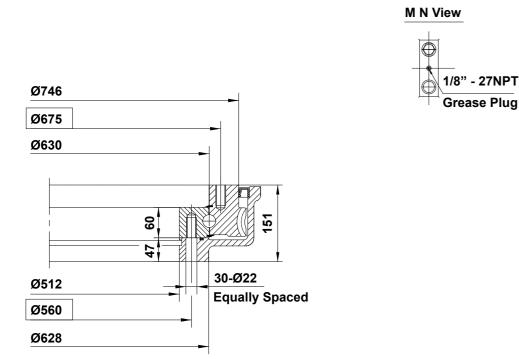
FWA25 - Moment Load Chart



Notice: Please be sure to remain under this curve.

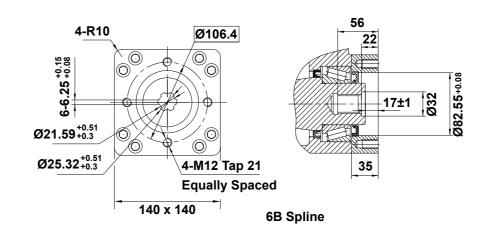
28

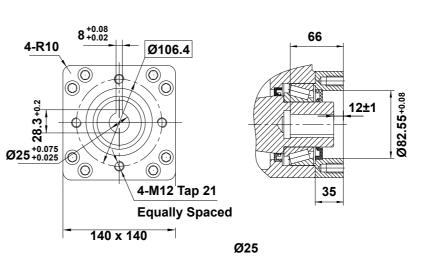




Units: mm Weight: 270kg

INPUT



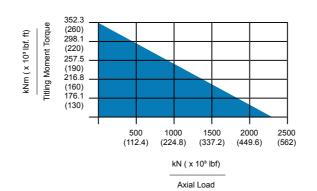




FWA25-2 - Slewing Drive Performance Parameters

Model	Output Torque	Tilting Moment Torque	Holding Torque	Axial Load	Radial Load	Ratio	Backlash	Weight
FIAMAGE O	58kNm	310kNm	275kNm	2400kN	950kN	108:1	≤0.13°	27010
FWA25-2	42800lbf.ft	229 x 10 ³ lbf.ft	203 x 10 ³ lbf	539.5 x 10 ³ lbf	213.6 x 10 ³ lbf	106.1	≥0.13	270kg

FWA25-2 - Moment Load Chart



Every effort has been taken to ensure that the data listed in this catalogue is correct.

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Notice: Please be sure to remain under this curve.

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TRANSDRIVE DRIVE

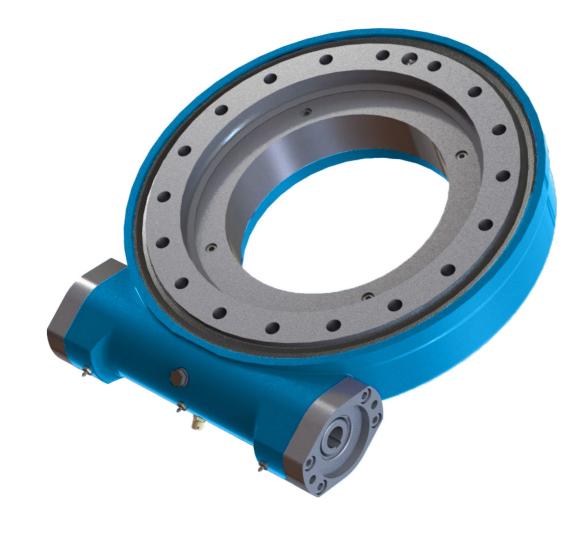
HSE Series

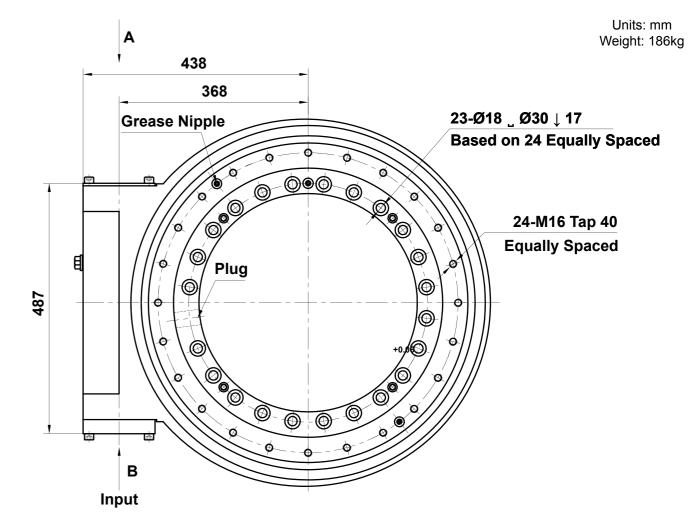
The HSE (High Speed Enclosed) Series features enclosed gearing for enhanced drive performance. This design offers superior protection against dust, moisture, and debris, increasing the drive system's durability and longevity.

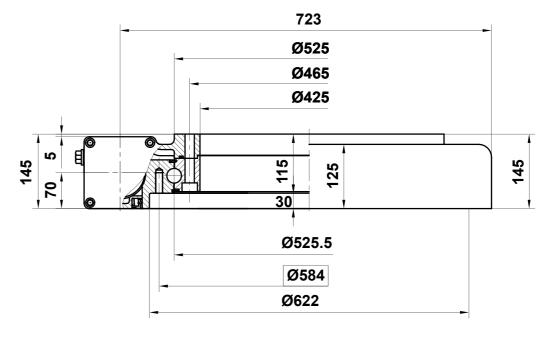
The improved performance ensures smoother, more efficient operation, reducing wear and maintenance needs. Ideal for demanding applications, the HSE Series delivers reliable functionality in tough conditions

Our range

- ► HSE21
- ► HSE21-2
- ► HSE25
- ► HSE25-2



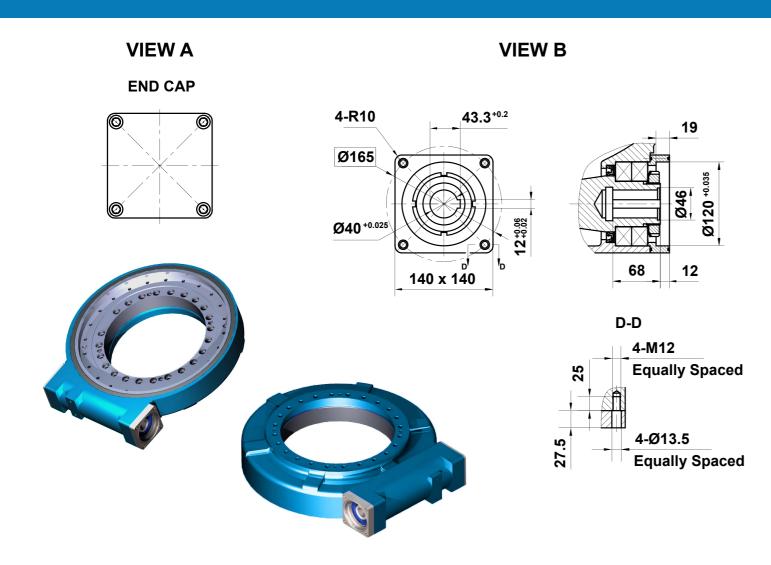






Units: mm

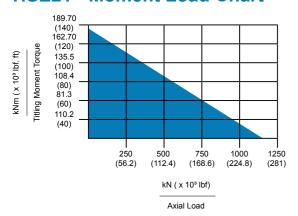
Weight: 206kg



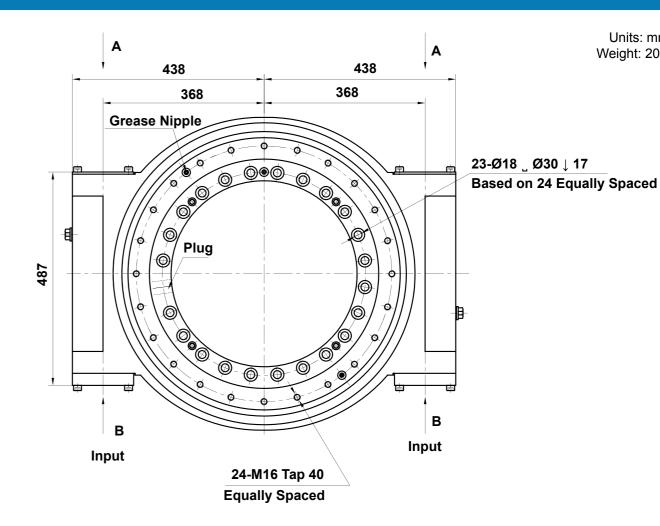
HSE21 - Worm Drive Performance Parameters

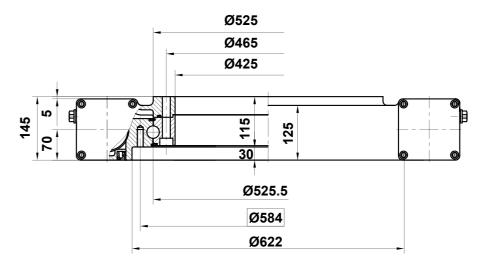
Model	Output Torque	Max Output Torque	Tilting Moment Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
HSE21	21.8kNm	26.6kNm	167kNm	1058kN	421kN	265kN	216kN	82:1	≤0.15°	196ka
HSEZI	16078lbf.ft	19618lbf.ft	125 x 10³lbf.ft	238 x 10 ³ lbf	95 x 10 ³ lbf	60 x 10 ³ lbf	49 x 10 ³ lbf	02.1	20.10	186kg

HSE21 - Moment Load Chart



Notice: Please be sure to remain under this curve.





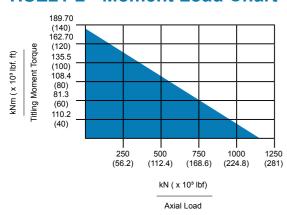
Ø40 ■ NORMAL

VIEW A OPTION VIEW B OPTION 4-R10 43.3+0.2 **END CAP** Ø165 **6** Ø120 +0.0 **Ø46** Ø40 +0.025 68 12 140 x 140 D-D 4-M12 **Equally Spaced** 4-Ø13.5 **Equally Spaced**

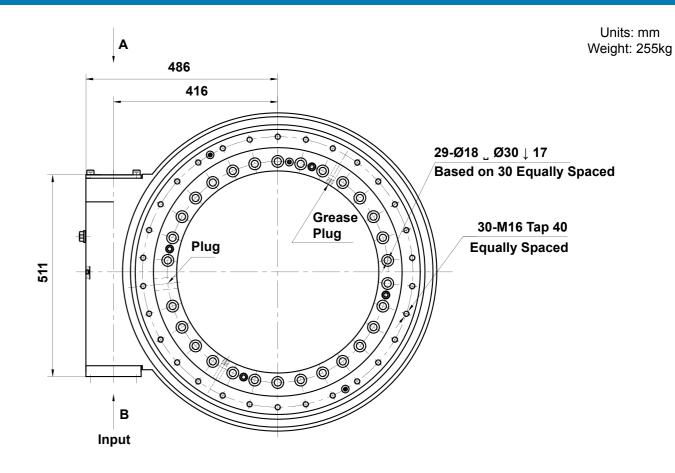
HSE21-2 - Worm Drive Performance Parameters

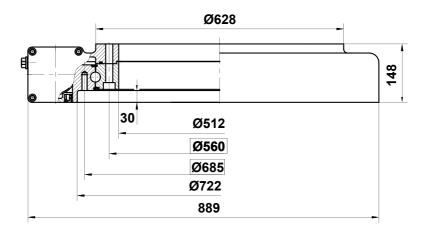
Model	Output Torque	Max Output Torque	Tilting Moment Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
HSE21-2	43.6kNm	52.3kNm	167kNm	1058kN	421kN	265kN	216kN	82:1	≤0.15°	206kg
HSEZ1-Z	32264lbf.ft	38702lbf.ft	125 x 10³lbf.ft	238 x 10 ³ lbf	95 x 10³lbf	60 x 10 ³ lbf	49 x 10³lbf	02.1	20.15	200kg

HSE21-2 - Moment Load Chart

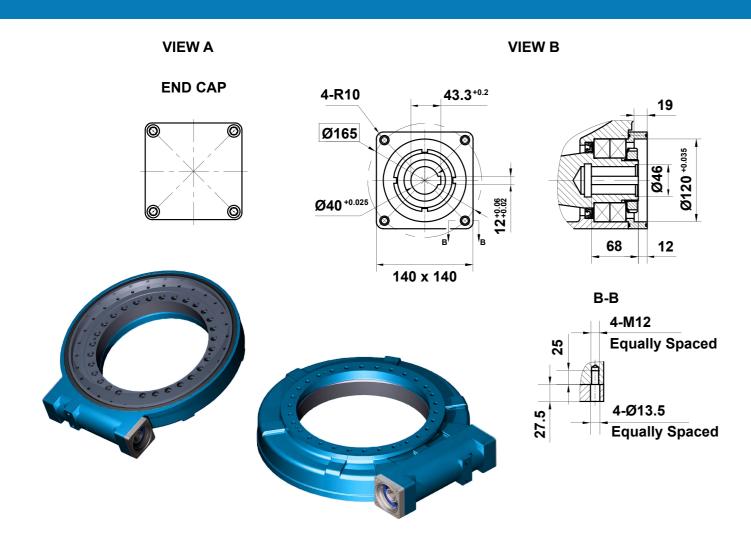


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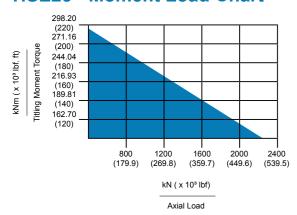




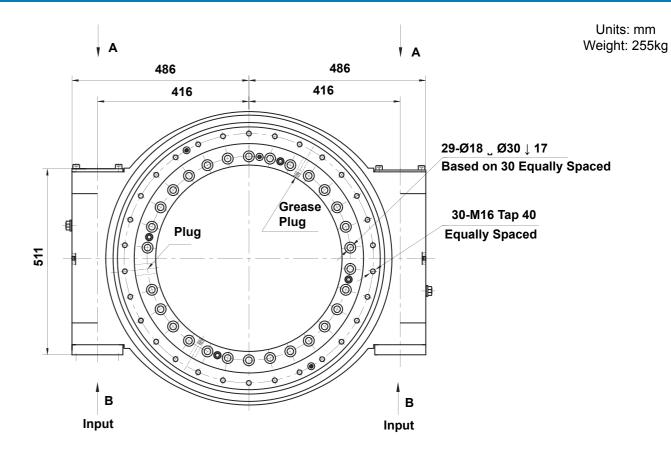
HSE25 - Worm Drive Performance Parameters

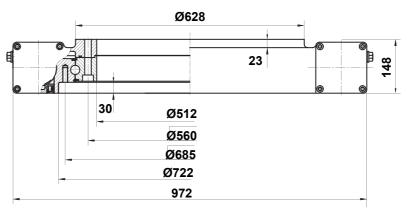
Model	Output Torque	Max Output Torque	Tilting Moment Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
HSE25	25kNm	30kNm	271kNm	1360kN	945kN	590kN	470kN	94:1	≤0.15°	OFFIce.
поЕ25	18439lbf.ft	22140lbf.ft	200 x 10 ³ lbf.ft	531 x 10 ³ lbf	212 x 10 ³ lbf	133 x 10 ³ lbf	106 x 10 ³ lbf	94. I	≥0.15	255kg

HSE25 - Moment Load Chart



Notice: Please be sure to remain under this curve.

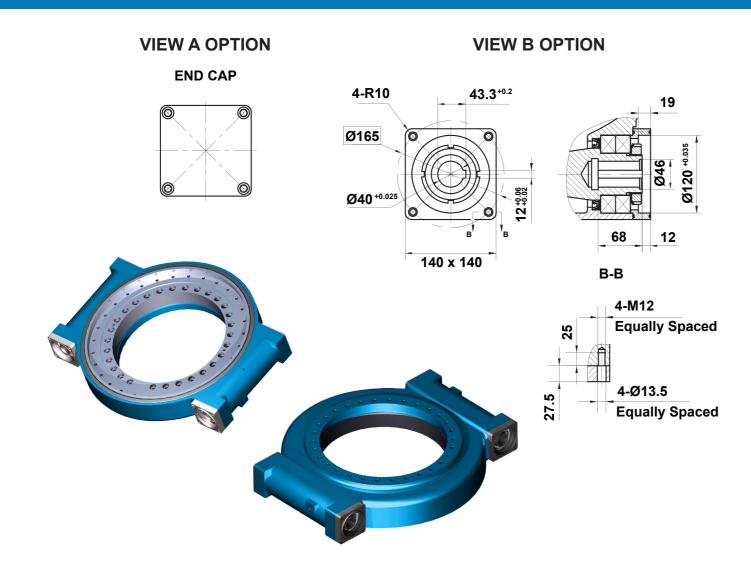




Ø40

□ NORMAL

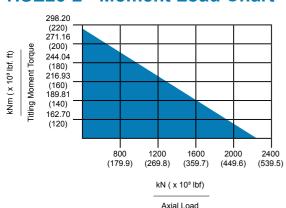




HSE25-2 - Worm Drive Performance Parameters

Model	Output Torque	Max Output Torque	Tilting Moment Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
HSE25	50kNm	60kNm	271kNm	1360kN	945kN	590kN	470kN	94:1	≤0.15°	275ka
ПSE25	36878lbf.ft	44280lbf.ft	200 x 10 ³ lbf.ft	531 x 10 ³ lbf	212 x 10 ³ lbf	133 x 10 ³ lbf	106 x 10 ³ lbf	94.1	≥0.15	275kg

HSE25-2 - Moment Load Chart



Notice: Please be sure to remain under this curve.

SE Series

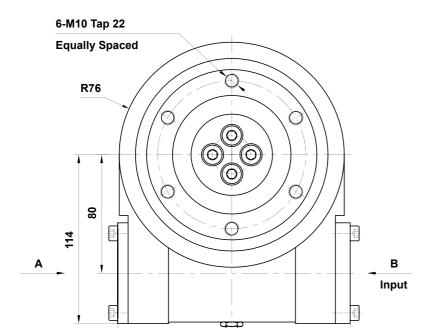
The SE (Slewing Enclosed) Series Slewing Drive is a compact and efficient solution designed to handle axial, radial, and tilting moment loads. It features an enclosed housing, slewing ring, worm, and support parts, allowing for precise rotation control and high torque capacity. The drive can be powered by either a hydraulic or electric motor, enabling clockwise and anticlockwise rotation.

The design allows for simple installation and easy maintenance, making it suitable for a wide range of applications such as solar energy, wind energy, construction, and manufacturing, where precise positioning and load handling are crucial

Our range

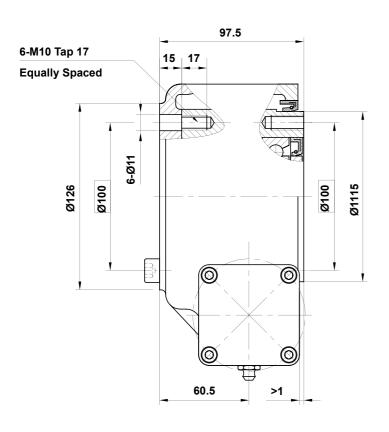
- ► SE3C/PE3C/ZE3C
- ► SE5A/PE5A/ZE5A
- ▶ SE5C/PE5C
- ► SE7/PE7/ZE7
- ► SE7A/PE7A
- ► SE9A/PE9A/ZE9A
- ► SE12A/PE12A/ZE12A
- ► SE14A/PE14A/ZE14A
- ► SE14-2/S14-2
- ► SE17A/PE17A
- ▶ SE17-2/S17-2
- ▶ SE21/PE21
- ▶ SE21-2/S21-2
- ▶ SE25/PE25
- ▶ SE25-2/S25-2



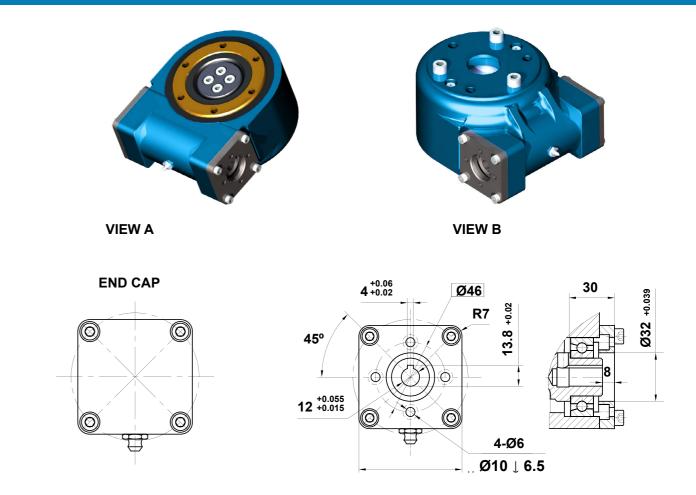


80

Units: mm Weight: 12kg



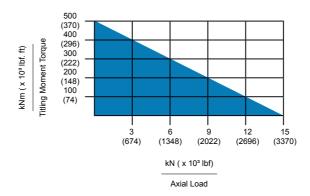
77



SE3C/PE3C/ZE3C - Slewing Drive Performance Parameters

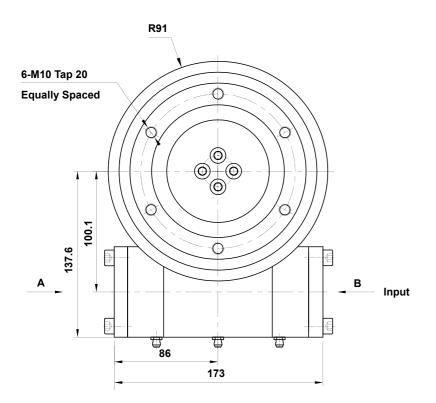
Output	Tilting Moment	Holding	Static Axial	Static Radial	Dynamic Axial	Dynamic	Gear Ratio	Tra	acking Precis	ion	Weight
Torque	Torque	Torque	Rating	Rating	Rating	Radial Rating	Geal Natio	SDE3	PDE3	ZDE3	weight
400Nm	500Nm	2000Nm	30kN	15kN	9.6kN	8.4kN	62:1	<0.2°	I: ≤0.08° II: ≤0.12°	0.0	201-
295lbf.ft	369lbf.ft	1475lbf.ft	6477lbf	3372lbf	2158lbf	1888lbf	02.1	≤0.2°	III: ≤0.12 III: ≤0.15°	00	32kg

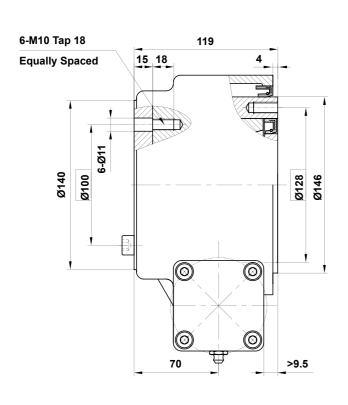
SE3C/PE3C/ZE3C - Moment Load Chart

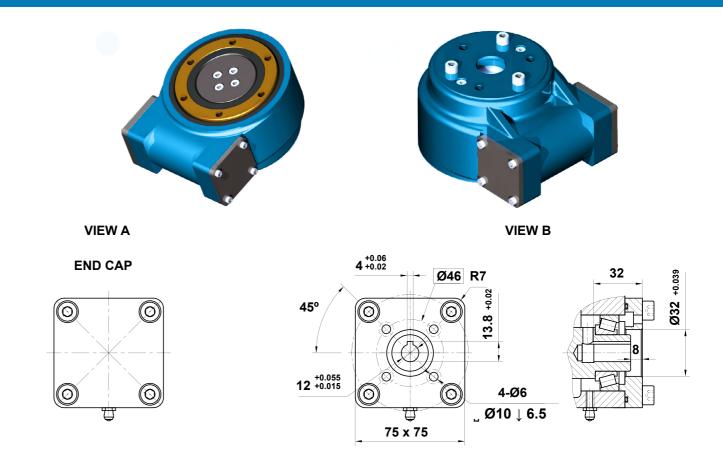


Notice: Please be sure to remain under this curve.





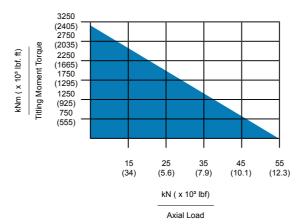




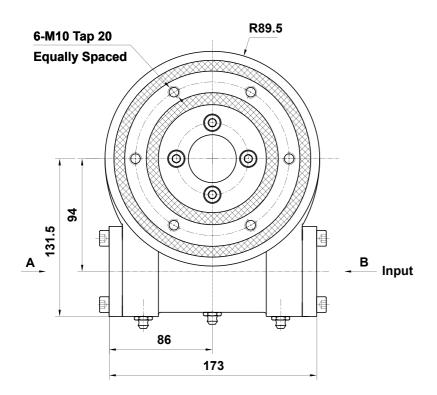
SE5A/PE5A/ZE5A - Slewing Drive Performance Parameters

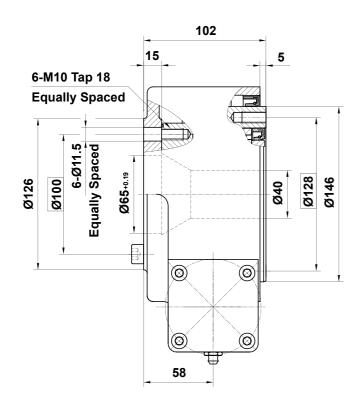
Model	Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
SE5A	600Nm	3000Nm	5500Nm	45kN	22kN	14.4kN	11.1kN	62:1	≤0.2°	20ka
SESA	442.5lbf.ft	2212.5lbf.ft	4056.25lbf.ft	10116lbf	4945.6lbf	3237.1lbf	2495.3lbf	62.1	≥0.2	20kg
PE5A	600Nm	3000Nm	5500Nm	45kN	22kN	14.4kN	11.1kN	62:1	I: ≤0.08° II: ≤0.12°	20kg
PESA	442.5lbf.ft	2212.5lbf.ft	4056.25lbf.ft	10116lbf	4945.6lbf	3237.1lbf	2495.3lbf	02.1	III: ≤0.12°	20kg
ZE5A	360Nm	3000Nm	5500Nm	45kN	22kN	14.4kN	11.1kN	62-1	00	20kg
ZLJA	265.5lbf.ft	2212.5lbf.ft	4056.25lbf.ft	10116lbf	4945.6lbf	3237.1lbf	2495.3lbf	62:1	00	20kg

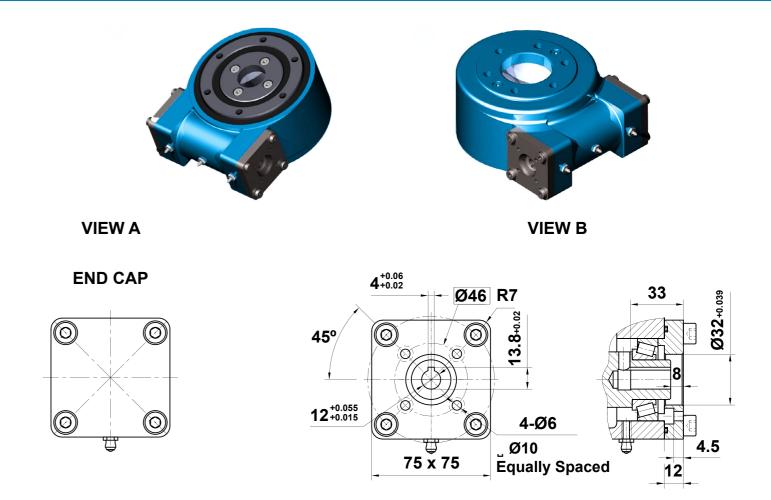
SE5A/PE5A/ZE5A - Moment Load Chart







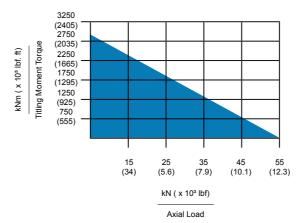




SE5C/PE5C - Slewing Drive Performance Parameters

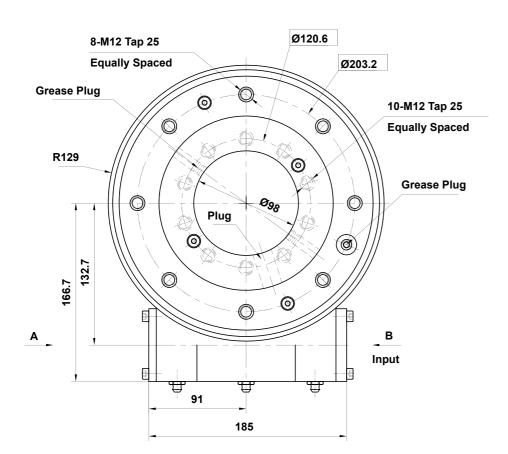
Model	Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
SE5A	600Nm	3000Nm	5500Nm	45kN	22kN	14.4kN	11.1kN	62:1	<0.2°	20kg
SESA	442.5lbf.ft	2212.5lbf.ft	4056.25lbf.ft	10116lbf	4945.6lbf	3237.1lbf	2495.3lbf	62.1	≤0.2°	20Kg
PE5A	600Nm	3000Nm	5500Nm	45kN	22kN	14.4kN	11.1kN	62:1	I: ≤0.08° II: ≤0.12°	201
PEJA	442.5lbf.ft	2212.5lbf.ft	4056.25lbf.ft	10116lbf	4945.6lbf	3237.1lbf	2495.3lbf	62.1	II. ≤0.12 III: ≤0.15°	20kg

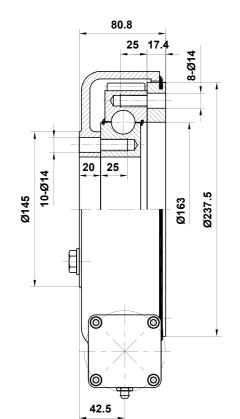
SE5C/PE5C - Moment Load Chart

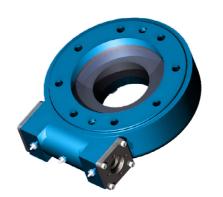


Units: mm

Weight: 21kg



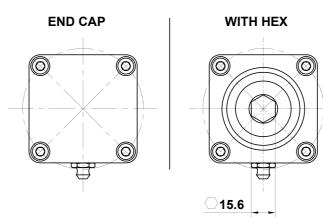


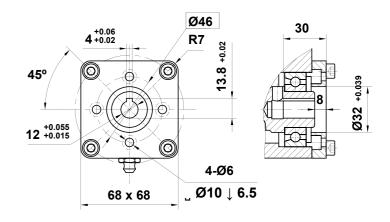




VIEW A OPTION

VIEW B

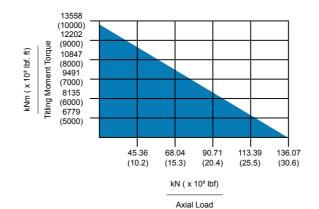




SE7/PE7/ZE7 - Slewing Drive Performance Parameters

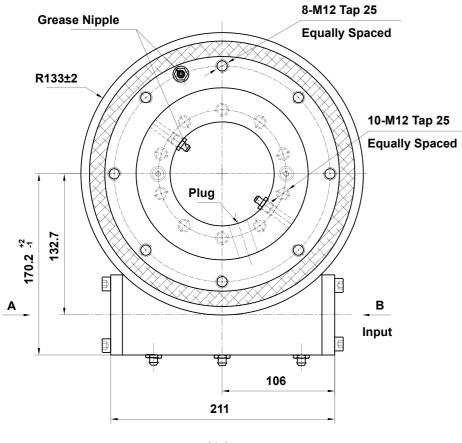
Model	Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
SE7	1500Nm	13500Nm	10400Nm	133kN	53kN	32kN	28kN	73:1	<0.2°	241.0
SE/	1107lbf.ft	9957lbf.ft	7671lbf.ft	29900lbf	11915lbf	7194lbf	6295lbf	73.1	≤0.2°	21kg
PE7	1500Nm	13500Nm	10400Nm	133kN	53kN	32kN	28kN	73:1	I: ≤0.05° II: ≤0.07°	241
PE/	1107lbf.ft	9957lbf.ft	7671lbf.ft	29900lbf	11915lbf	7194lbf	6295lbf	73.1	II. ≤0.07 III: ≤0.11°	21kg
757	600Nm	13500Nm	10400Nm	133kN	53kN	32kN	28kN	70.4		201
ZE7	44³lbf.ft	9957lbf.ft	7671lbf.ft	29900lbf	11915lbf	7194lbf	6295lbf	73:1	00	20kg

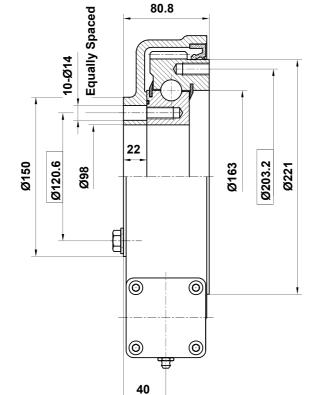
SE7/PE7/ZE7 - Moment Load Chart



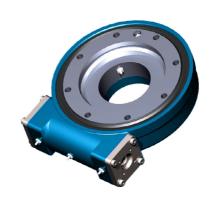
SE7A/PE7A







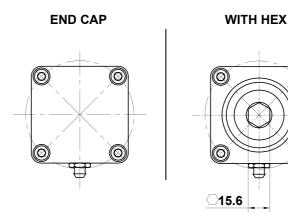
Units: mm Weight: 25kg

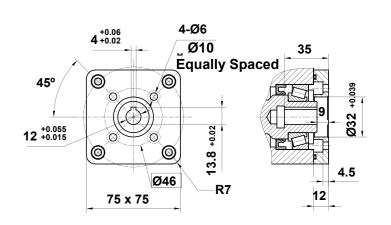




VIEW A OPTION

VIEW B

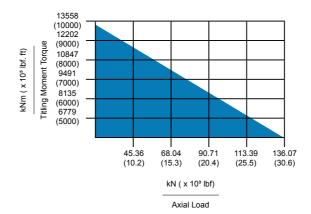




SE7A/PE7A - Slewing Drive Performance Parameters

Mode	l Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
SE7	1500Nm	13500Nm	10400Nm	133kN	53kN	32kN	28kN	73:1	≤0.2°	OEI.
SE/	1107lbf.ft	9957lbf.ft	7671lbf.ft	29900lbf	11915lbf	7194lbf	6295lbf	73.1	≥0.2	25kg
PE7	1500Nm	13500Nm	10400Nm	133kN	53kN	32kN	28kN	70.4	I: ≤0.05°	051
PE/	1107lbf.ft	9957lbf.ft	7671lbf.ft	29900lbf	11915lbf	7194lbf	6295lbf	73:1	II: ≤0.07° III: ≤0.11°	25kg

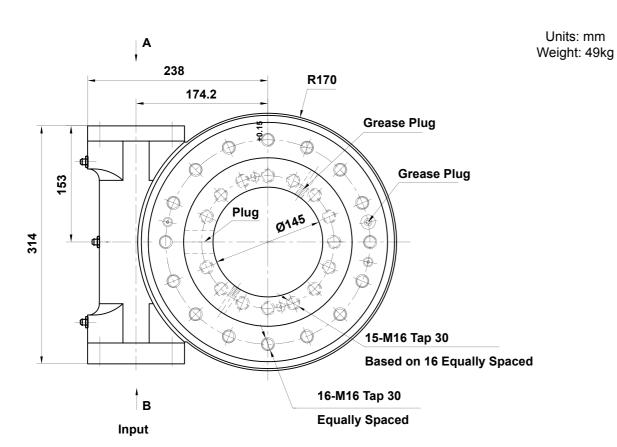
SE7A/PE7A- Moment Load Chart



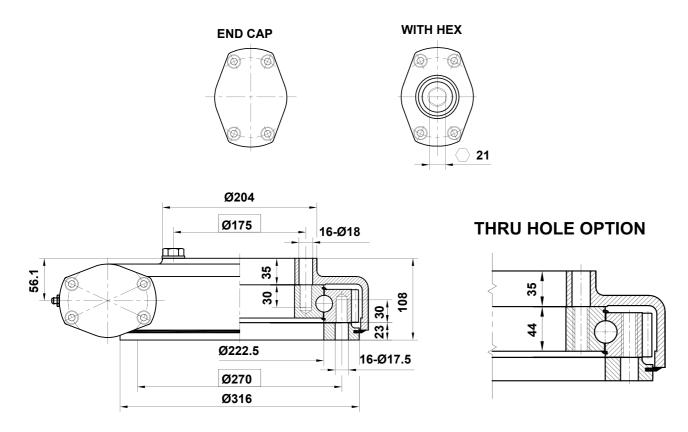
SE9A/PE9A/ZE9A

SE Series



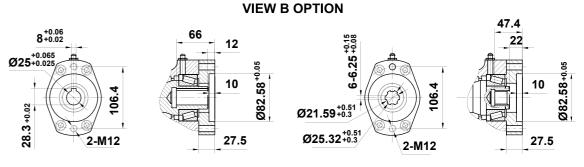


VIEW A OPTION









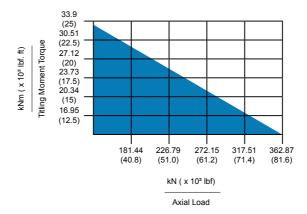
Ø12 Ø14 Ø16 Ø20 **Ø25** □ NORMAL

6B SPLINE

SE9A/PE9A/ZE9A - Worm Drive Performance Parameters

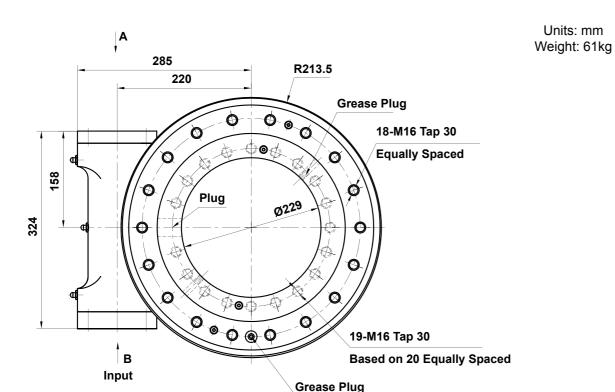
Model	Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
CEOA	6.5kNm	33.9kNm	38.7kNm	338kN	135kN	81kN	71kN	61:1	≤0.17°	4016
SE9A	4794lbf.ft	25 x 10 ³ lbf.ft	29 x 10 ³ lbf.ft	76 x 10 ³ lbf	30 x 10 ³ lbf	18 x 10³lbf	16 x 10³lbf	01.1	50.17	49kg
PE9A	6.5kNm	33.9kNm	38.7kNm	338kN	135kN	81kN	71kN	61:1	I: ≤0.05° II: ≤0.07°	4014
PE9A	4794lbf.ft	25 x 10 ³ lbf.ft	29 x 10 ³ lbf.ft	76 x 10 ³ lbf	30 x 10 ³ lbf	18 x 10³lbf	16 x 10³lbf	01.1	II. ≤0.07 III: ≤0.09°	49kg
ZE9A	3.9kNm	33.9kNm	38.7kNm	338kN	135kN	81kN	71kN	61:1	00	40kg
ZE9A	2876lbf.ft	25 x 10°lbf.ft	29 x 10³lbf.ft	76 x 10 ³ lbf	30 x 10 ³ lbf	18 x 10³lbf	16 x 10³lbf	01.1	00	49kg

SE9A/PE9A/ZE9A - Moment Load Chart

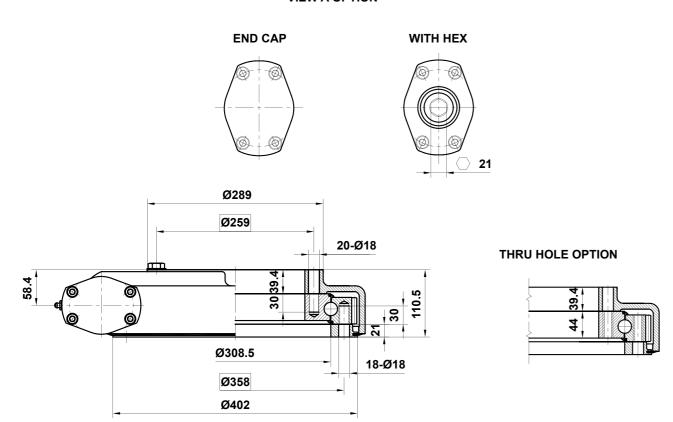


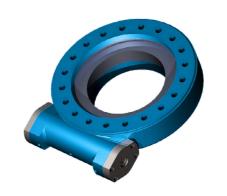
Notice: Please be sure to remain under this curve.



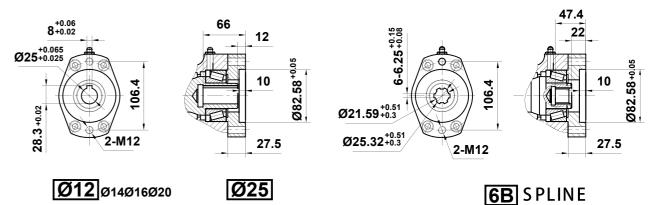


VIEW A OPTION





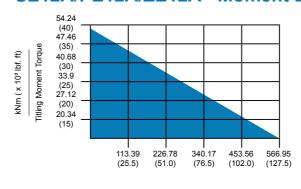




SE12A/PE12A/ZE12A - Worm Drive Performance Parameters

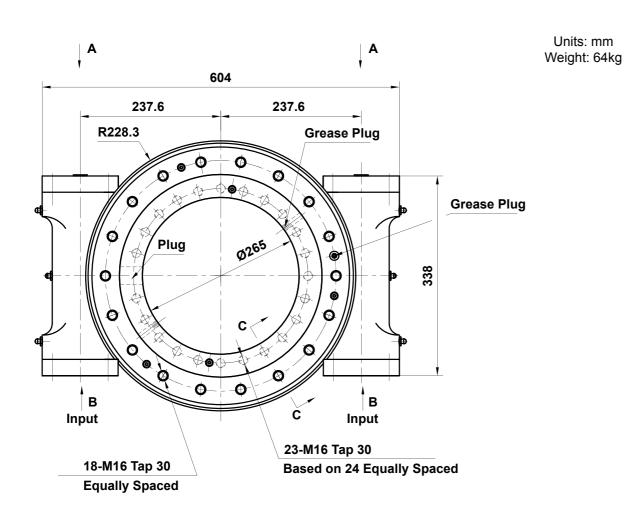
Model	Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
05404	7.5kNm	54.3kNm	43kNm	475kN	190kN	114kN	100kN	78:1	≤0.17°	Cale
SE12A	5532lbf.ft	40 x 10³lbf.ft	32 x 10 ³ lbf.ft	107 x 10 ³ lbf	43 x 10 ³ lbf	26 x 10 ³ lbf	23 x 10³lbf	70.1	≥0.17	61kg
PE12A	7.5kNm	54.3kNm	43kNm	475kN	190kN	114kN	100kN	78:1	I: ≤0.03o II: ≤0.05°	Cale
PEIZA	5532lbf.ft	40 x 10³lbf.ft	32 x 10 ³ lbf.ft	107 x 10 ³ lbf	43 x 10 ³ lbf	26 x 10 ³ lbf	23 x 10³lbf	70.1	III: ≤0.09°	61kg
ZE12A	4.5kNm	54.3kNm	43kNm	475kN	190kN	114kN	100kN	78:1	00	641.0
ZE1ZA	3319lbf.ft	40 x 10 ³ lbf.ft	32 x 10 ³ lbf.ft	107 x 10 ³ lbf	43 x 10 ³ lbf	26 x 10 ³ lbf	23 x 10³lbf	70:1	00	61kg

SE12A/PE12A/ZE12A - Moment Load Chart

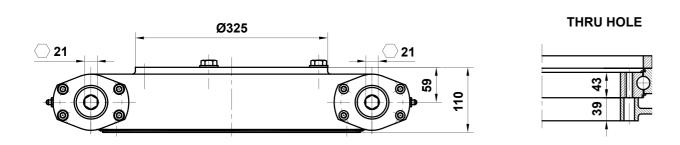


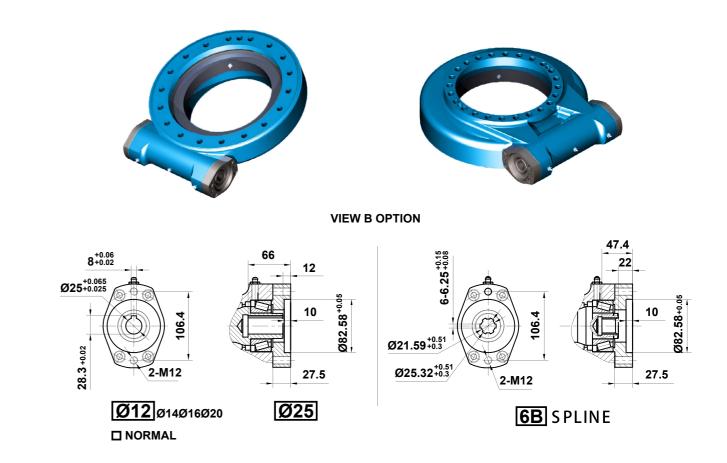
□ NORMAL

Notice: Please be sure to remain under this curve.



WITH HEX Ø435.5 Ø390 18-Ø17.5 Ø342.5 8 Ø295 24-Ø18

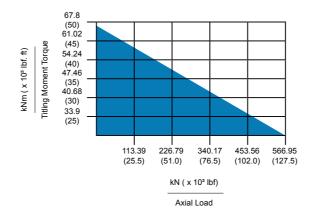




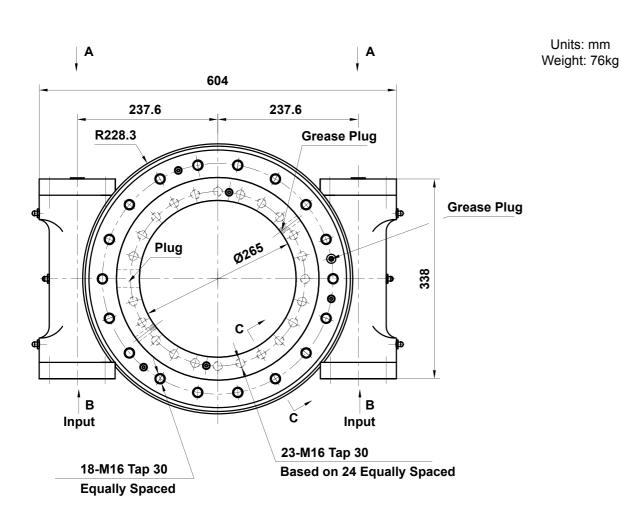
SE14A/PE14A/ZE14A - Worm Drive Performance Parameters

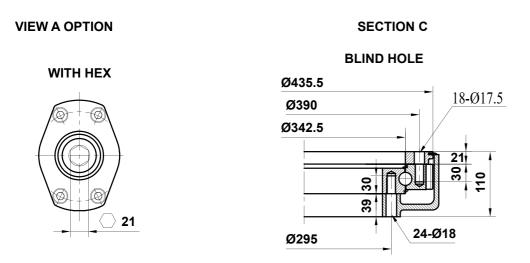
Model	Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
SE14A	8kNm	67.8kNm	48kNm	555kN	222kN	133kN	117kN	85:1	≤0.17°	64kg
3E 14A	5900lbf.ft	50 x 10 ³ lbf.ft	35 x 10°lbf.ft	125 x 10 ³ lbf	50 x 10 ³ lbf	30 x 10 ³ lbf	26 x 10 ³ lbf	05.1	20.17	04Kg
	8kNm	67.8kNm	48kNm	555kN	222kN	133kN	117kN		I: ≤0.03o II: ≤0.05°	
PE14A	5900lbf.ft	50 x 10 ³ lbf.ft	35 x 10³lbf.ft	125 x 10 ³ lbf	50 x 10 ³ lbf	30 x 10 ³ lbf	26 x 10 ³ lbf	85:1	III: ≤0.07° IV: ≤0.09°	64kg
ZE14A	4.8kNm	67.8kNm	48kNm	555kN	222kN	133kN	117kN	85:1	00	64kg
ZEI4A	3500lbf.ft	50 x 10 ³ lbf.ft	35 x 10³lbf.ft	125 x 10³lbf	50 x 10 ³ lbf	30 x 10 ³ lbf	26 x 10 ³ lbf	65.1	00	04kg

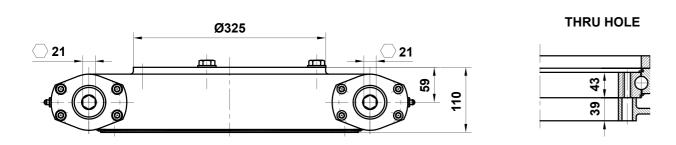
SE14A/PE14A/ZE14A - Moment Load Chart

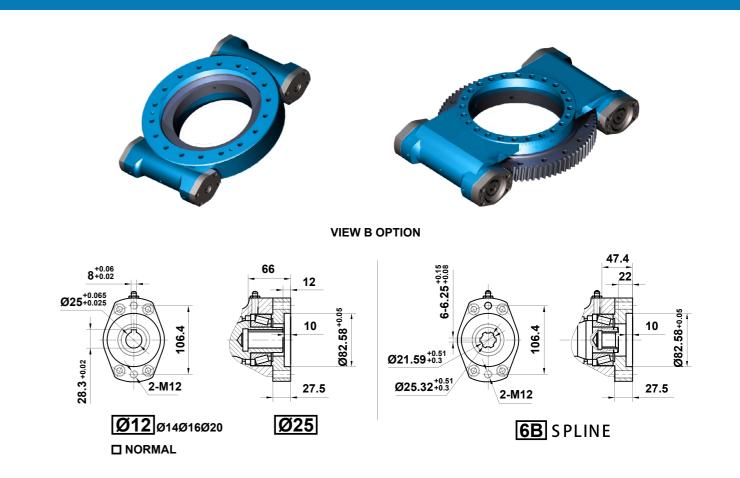


Notice: Please be sure to remain under this curve.





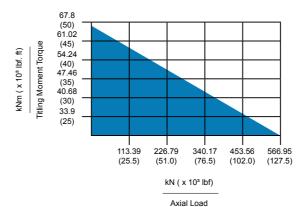




SE14-2/S14-2 - Worm Drive Performance Parameters

M	lodel	Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
C.F.	E14-2	12kNm	67.8kNm	48kNm	555kN	222kN	133kN	117kN	85:1	≤0.17°	761.0
SE	= 14-2	8851lbf.ft	50 x 10 ³ lbf.ft	35 x 10 ³ lbf.ft	125 x 10 ³ lbf	50 x 10 ³ lbf	30 x 10 ³ lbf	26 x 10³lbf	00.1	50.17	76kg
	14-2	8kNm	67.8kNm	48kNm	555kN	222kN	133kN	117kN	85:1	≤0.17°	761.0
5	14-2	5900lbf.ft	50 x 10 ³ lbf.ft	35 x 10 ³ lbf.ft	125 x 10 ³ lbf	50 x 10 ³ lbf	30 x 10 ³ lbf	26 x 10³lbf	05.1	50.17	76kg

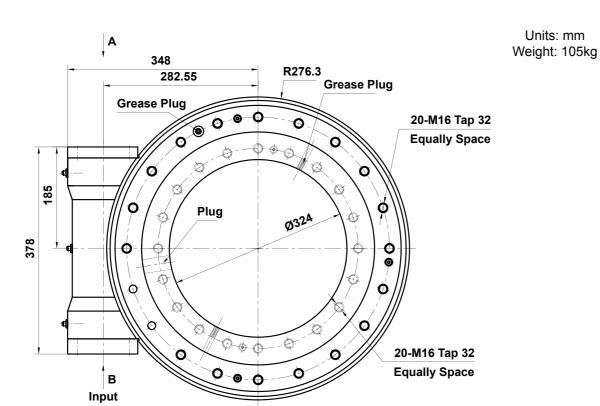
SE14-2/S14-2 - Moment Load Chart



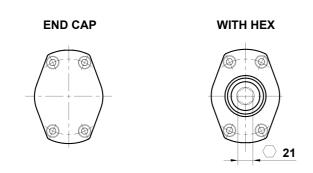
Notice: Please be sure to remain under this curve.

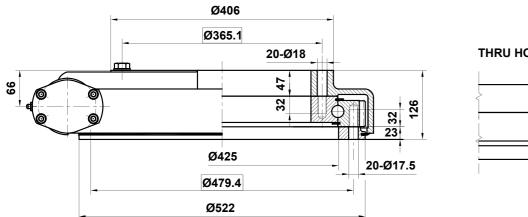
Units: mm

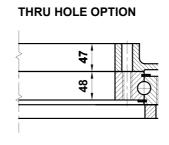
SE Series



VIEW A OPTION





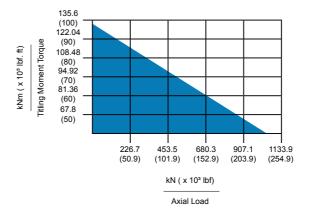




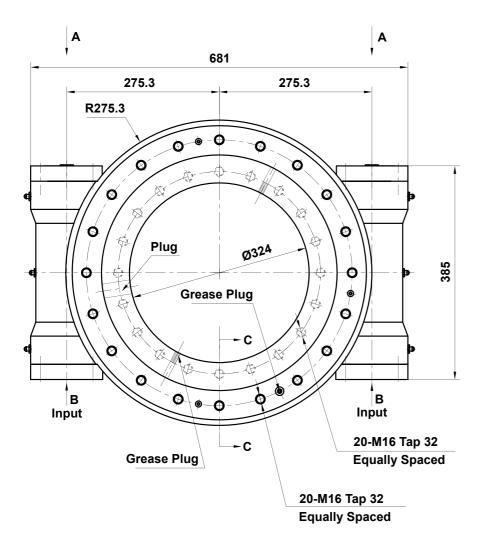
SE17A/PE17A - Worm Drive Performance Parameters

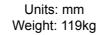
Model	Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
SE17A	10kNm	135.6kNm	72.3kNm	970kN	390kN	235kN	205kN	102:1	≤0.15°	10Eka
SEITA	7400lbf.ft	100 x 10 ³ lbf.ft	53 x 10 ³ lbf.ft	218 x 10 ³ lbf	88 x 10 ³ lbf	53 x 10 ³ lbf	46 x 10 ³ lbf	102.1	≥0.15	105kg
DE474	10kNm	135.6kNm	72.3kNm	970kN	390kN	235kN	205kN	400:4	40.45°	4051
PE17A	7400lbf.ft	100 x 10 ³ lbf.ft	53 x 10 ³ lbf.ft	218 x 10 ³ lbf	88 x 10 ³ lbf	53 x 10 ³ lbf	46 x 10 ³ lbf	102:1	≤0.15°	105kg

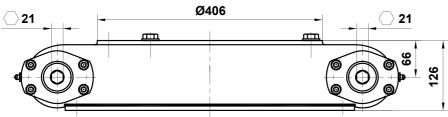
SE17A/PE17A - Moment Load Chart

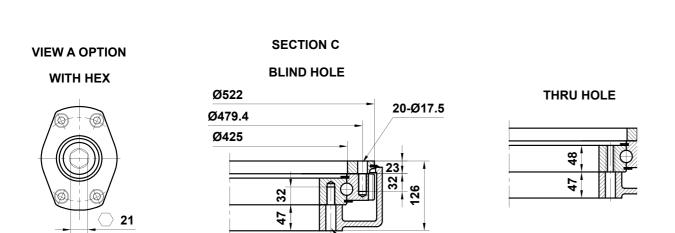


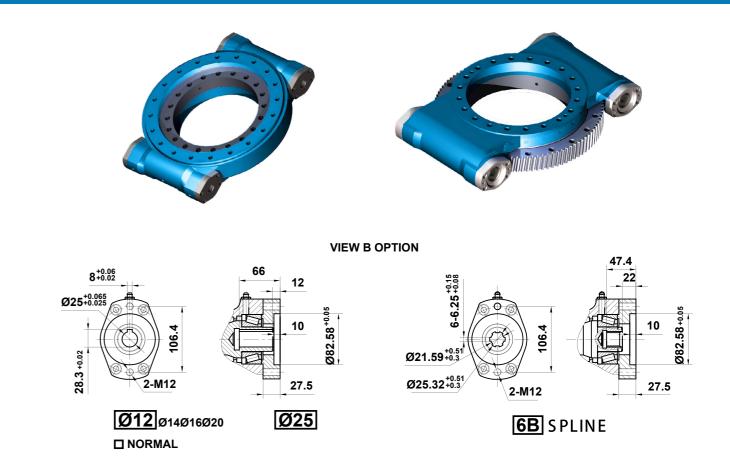








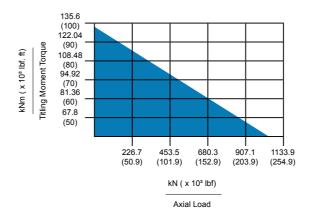


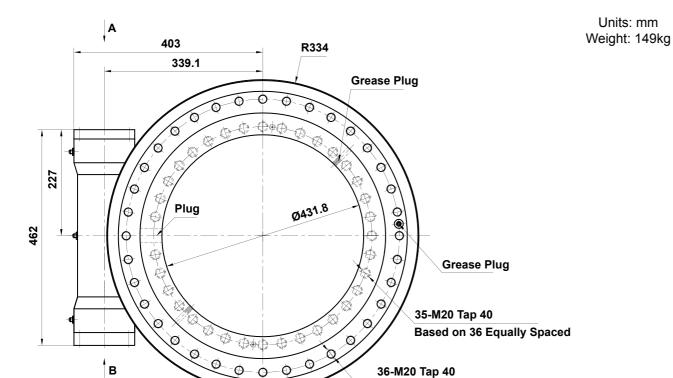


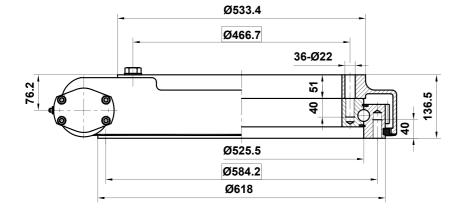
SE17A/PE17A - Worm Drive Performance Parameters

Model	Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
SE17-2	16.8kNm	135.6kNm	72.3kNm	970kN	390kN	235kN	205kN	102:1	≤0.15°	119kg
SE17-2	12391lbf.ft	100 x 10 ³ lbf.ft	53 x 10 ³ lbf.ft	218 x 10 ³ lbf	88 x 10 ³ lbf	53 x 10³lbf	46 x 10 ³ lbf	102.1	≥0.15	119kg
047.0	10kNm	135.6kNm	72.3kNm	970kN	390kN	235kN	205kN	100.1	<0.15°	400km
S17-2	7400lbf.ft	100 x 10 ³ lbf.ft	53 x 10 ³ lbf.ft	218 x 10 ³ lbf	88 x 10 ³ lbf	53 x 10³lbf	46 x 10 ³ lbf	102:1	≤0.15°	102kg

SE17A/PE17A - Moment Load Chart

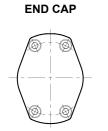


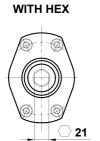




VIEW A OPTION

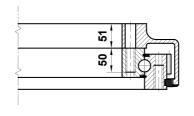
Input

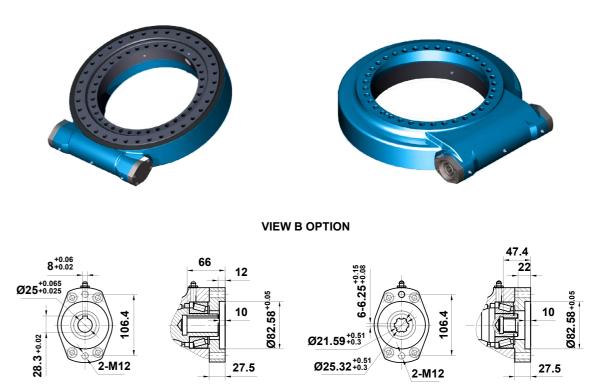




THRU HOLE OPTION

Equally Spaced





SE21/PE21 - Worm Drive Performance Parameters

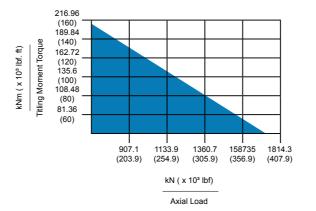
Ø12 Ø14Ø16Ø20

□NORMAL

Ø25

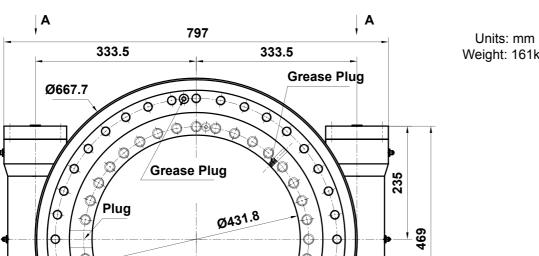
Мо	del	Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
SE	-04	15kNm	203kNm	105.8kNm	1598kN	640kN	385kN	335kN	125:1	≤0.15°	1401-
SE	:21	11000lbf.ft	150 x 10 ³ lbf.ft	78 x 10 ³ lbf.ft	359 x 10 ³ lbf	144 x 10³lbf	87 x 10 ³ lbf	75 x 10³lbf	125.1	≥0.15	149kg
PE	-04	15kNm	203kNm	105.8kNm	1598kN	640kN	385kN	335kN	125:1	≤0.15°	1401-
PE	21	11000lbf.ft	150 x 10 ³ lbf.ft	78 x 10 ³ lbf.ft	359 x 10 ³ lbf	144 x 10³lbf	87 x 10 ³ lbf	75 x 10³lbf	125.1	≥0.15	149kg

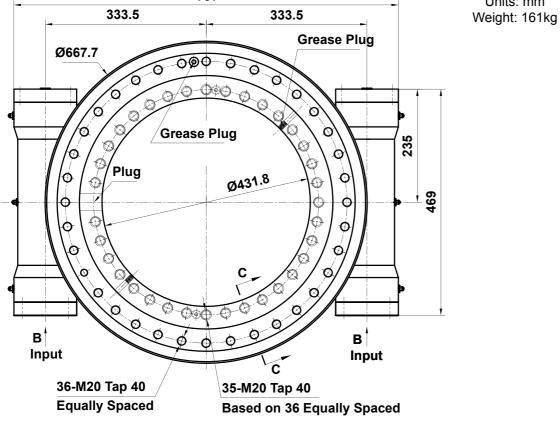
SE21/PE21 - Moment Load Chart

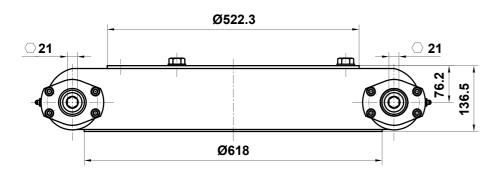


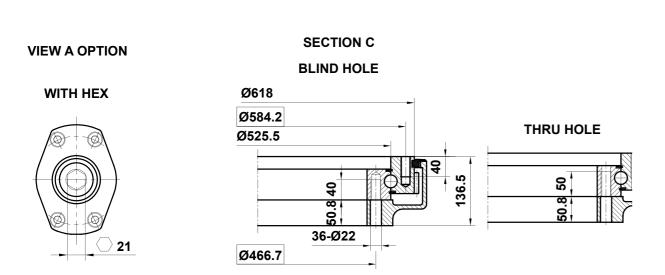
Notice: Please be sure to remain under this curve.

6B SPLINE











SE21-2/S21-2 - Worm Drive Performance Parameters

Model	Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
SE21-2	20.6kNm	203kNm	105.8kNm	1598kN	640kN	385kN	335kN	125:1	≤0.15°	1401
SE21-2	15194lbf.ft	150 x 10 ³ lbf.ft	78 x 10 ³ lbf.ft	359 x 10 ³ lbf	144 x 10³lbf	87 x 10 ³ lbf	75 x 10³lbf	125.1	20.15	149kg
004.0	20.6kNm	203kNm	105.8kNm	1598kN	640kN	385kN	335kN	405.4	40.45°	4.401
S21-2	15194lbf.ft	150 x 10 ³ lbf.ft	78 x 10 ³ lbf.ft	359 x 10 ³ lbf	144 x 10 ³ lbf	87 x 10 ³ lbf	75 x 10³lbf	125:1	≤0.15°	149kg

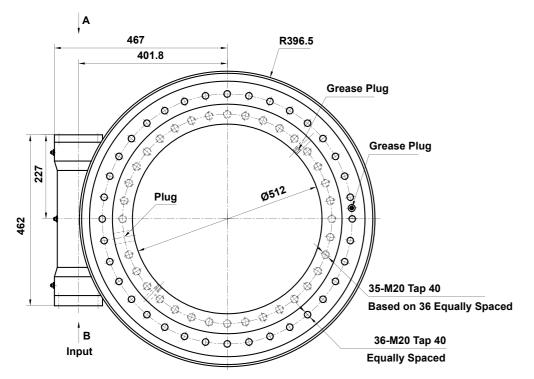
SE21-2/S21-2 - Moment Load Chart

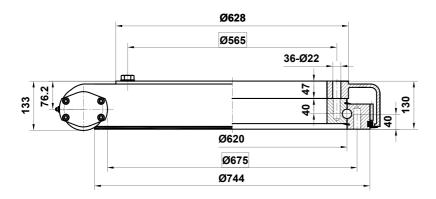


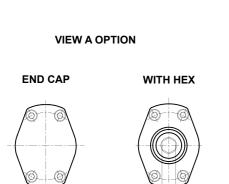
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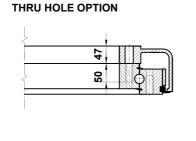


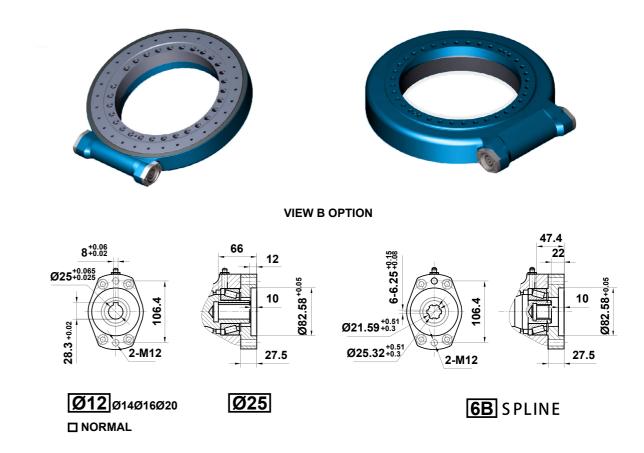
Units: mm Weight: 204kg







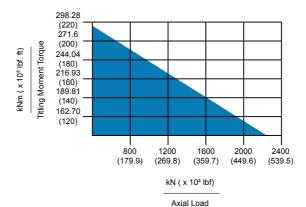




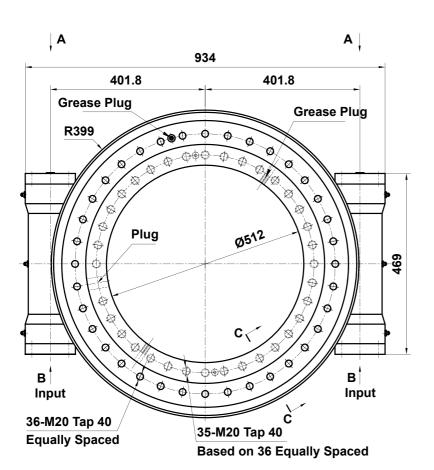
SE25/PE25 - Worm Drive Performance Parameters

Model	Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
SE25	18kNm	271kNm	158.3kNm	2360kN	945kN	590kN	470kN	150:1	≤0.15°	204kg
SEZS	13300lbf.ft	200 x 10 ³ lbf.ft	117 x 10³lbf.ft	531 x 10 ³ lbf	212 x 10 ³ lbf	133 x 10 ³ lbf	106 x 10 ³ lbf	150.1	20.13	204kg
	18kNm	271kNm	158.3kNm	2360kN	945kN	590kN	470kN		I: ≤0.03o II: ≤0.05°	
PE25	13300lbf.ft	200 x 10 ³ lbf.ft	117 x 10 ³ lbf.ft	531 x 10 ³ lbf	212 x 10³lbf	133 x 10³lbf	106 x 10 ³ lbf	150:1	III: ≤0.05° IV: ≤0.09°	204kg

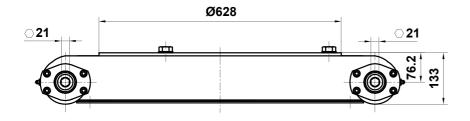
SE25/PE25 - Moment Load Chart

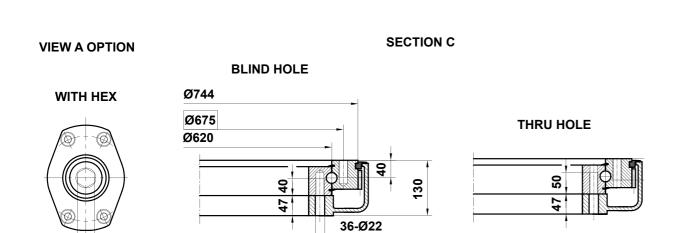


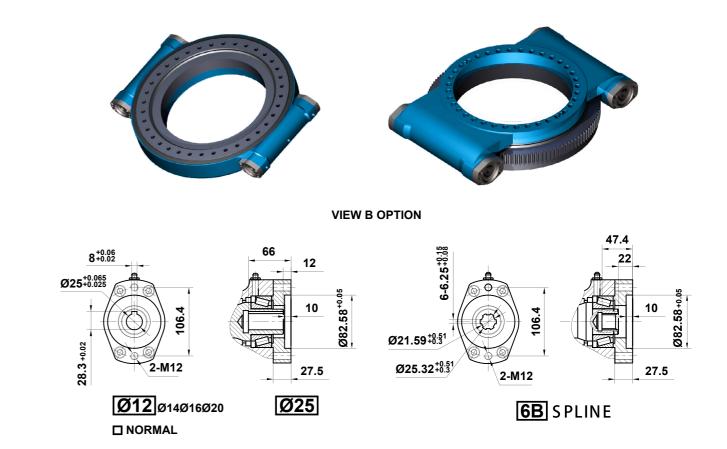




Units: mm Weight: 222kg



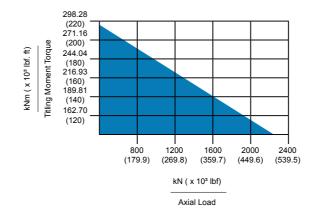




SE25-2/S25-2 - Worm Drive Performance Parameters

Model	Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
SE25-2	28kNm	271kNm	158.3kNm	2360kN	945kN	590kN	470kN	150:1	≤0.15°	2221.2
SE25-2	20652lbf.ft	200 x 10 ³ lbf.ft	117 x 10 ³ lbf.ft	531 x 10 ³ lbf	212 x 10 ³ lbf	133 x 10 ³ lbf	106 x 10 ³ lbf	150.1	≥0.15	222kg
005.0	28kNm	271kNm	158.3kNm	2360kN	945kN	590kN	470kN	450.4	40.45°	00.41
S25-2	20652lbf.ft	200 x 10 ³ lbf.ft	117 x 10 ³ lbf.ft	531 x 10 ³ lbf	212 x 10 ³ lbf	133 x 10 ³ lbf	106 x 10 ³ lbf	150:1	≤0.15°	204kg

SE25-2/S25-2 - Moment Load Chart



Notice: Please be sure to remain under this curve.

Ø565

≥ 21

TRANSDRIVE® DRIVE PERFORMANCE

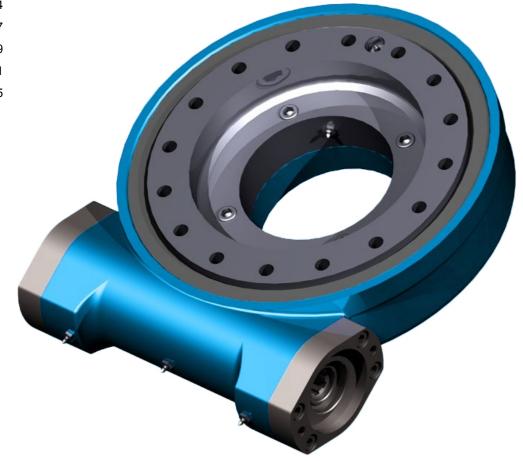
WEA Series

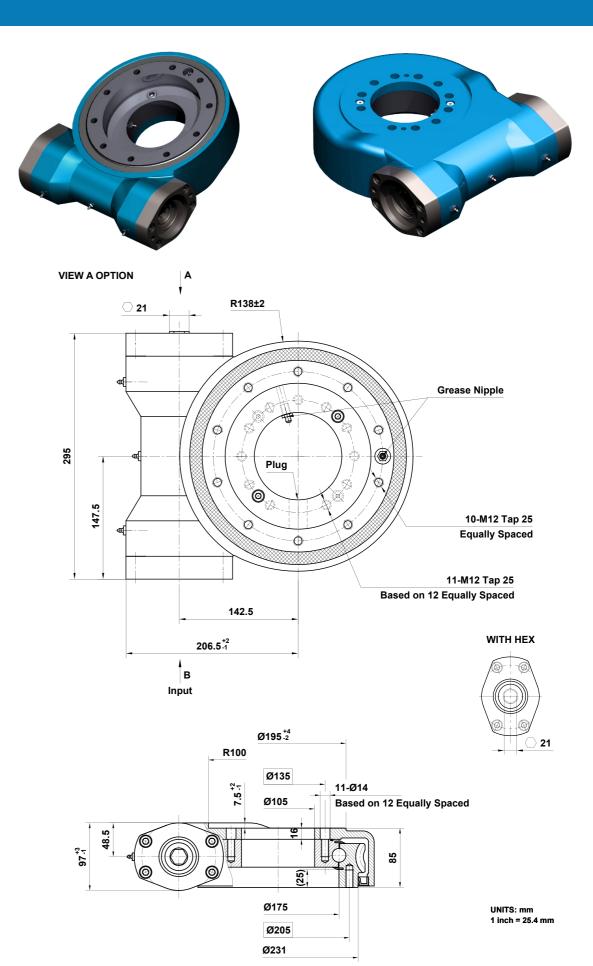
The WEA (Worm Enclosed Advanced) Series combines robust construction with enclosed gearing for superior protection and performance. Designed to withstand harsh environments, the WEA Series offers excellent durability and longevity by shielding against dust, moisture, and debris. This series ensures efficient, reliable operation, making it perfect for heavy-duty applications where consistent performance is crucial.

The key advantages of worm drives include their high reduction ratios, compact size, quiet operation, and the ability to provide a self-locking feature, which makes them suitable for applications where backdriving (reversing the direction of power flow) needs to be prevented.

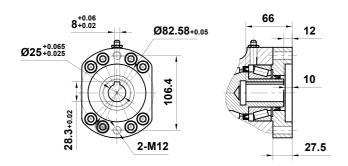
Our range

- ► WEA7
- ► WEA9
- ► WEA12
- ► WEA14
- ► WEA17
- ▶ WEA19
- ▶ WEA21
- ► WEA25





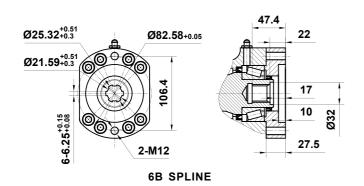




<u>Ø12</u> Ø14 Ø16 Ø20 <u>Ø25</u>

□ NORMAL

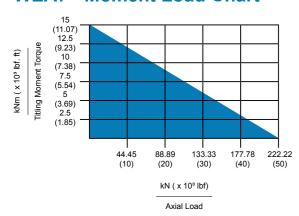
UNITS: mm 1 inch = 25.4 mm



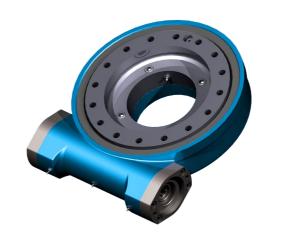
WEA7 - Worm Drive Performance Parameters

Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
3.5 kN.m	14.2 kN.m	20 kN.m	220 kN	90 kN	63 kN	48 kN	47:1	≤ 0.150	35kg
2583 lbf.ft	10.5 x 10 ³ lbf.ft	14.8 x 10 ³ lbf.ft	49.5 x 10 ³ lbf	20.2 x 10 ³ lbf	14.2 x 10 ³ lbf	10.8 x 10 ³ lbf			

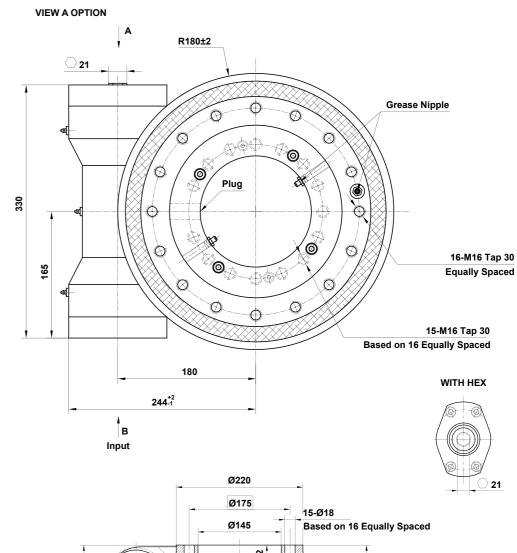
WEA7 - Moment Load Chart

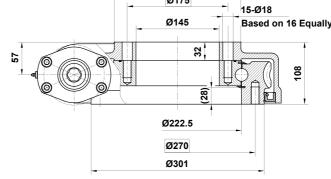


Notice: Please be sure to remain under this curve.



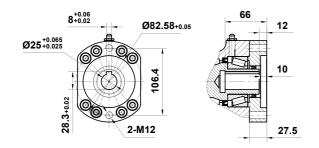






transdrive.com.au

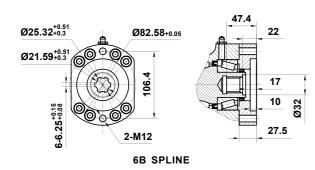
74



Ø12 Ø14 Ø16 Ø20 <u>Ø25</u>

□NORMAL

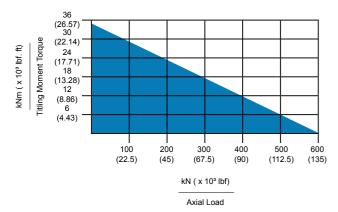
UNITS: mm 1 inch = 25.4 mm



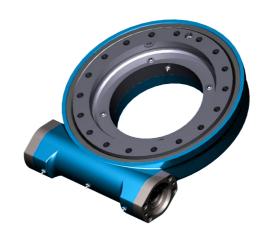
WEA9 - Worm Drive Performance Parameters

Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
8 kN.m	35.6 kN.m	38.7 kN.m	578 kN	215 kN	136 kN	115 kN	62:1	≤ 0.150	E2ka
5904 lbf.ft	26.3 x 10 ³ lbf.ft	29 x 10 ³ lbf.ft	129.9 x 10 ³ lbf	48.3 x 10 ³ lbf	30.6 x 10 ³ lbf	25.9 x 10 ³ lbf	02.1	≥ 0.150	53kg

WEA9 - Moment Load Chart

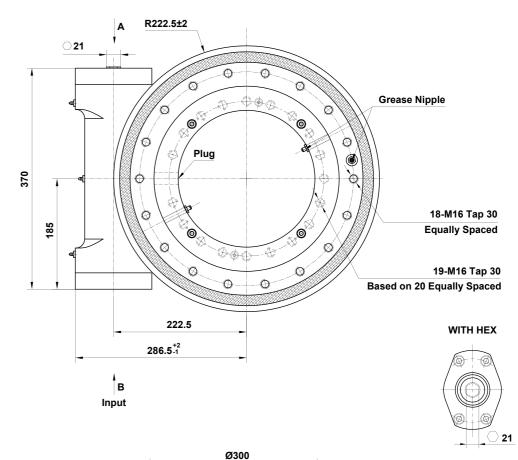


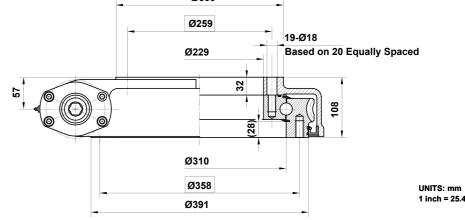
Notice: Please be sure to remain under this curve.



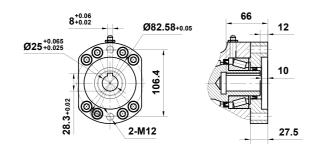


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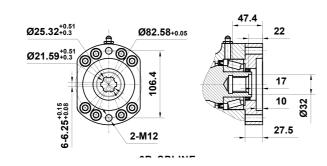




<u>Ø12</u> Ø14 Ø16 Ø20 <u>Ø25</u>

□NORMAL

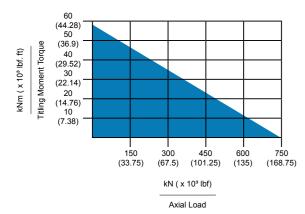
UNITS: mm 1 inch = 25.4 mm



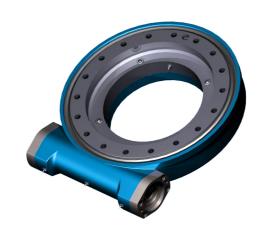
WEA12 - Worm Drive Performance Parameters

Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
9.5 kN.m	57 kN.m	43 kN.m	760 kN	280 kN	190 kN	148 kN	79:1	≤ 0.150	66.8kg
7011 lbf.ft	42.1 x 10 ³ lbf.ft	32 x 10 ³ lbf.ft	171.1 x 10 ³ lbf	62.9 x 10 ³ lbf	42.7 x 10 ³ lbf	33.3 x 10 ³ lbf	79.1	≥ 0.150	oo.okg

WEA12 - Moment Load Chart

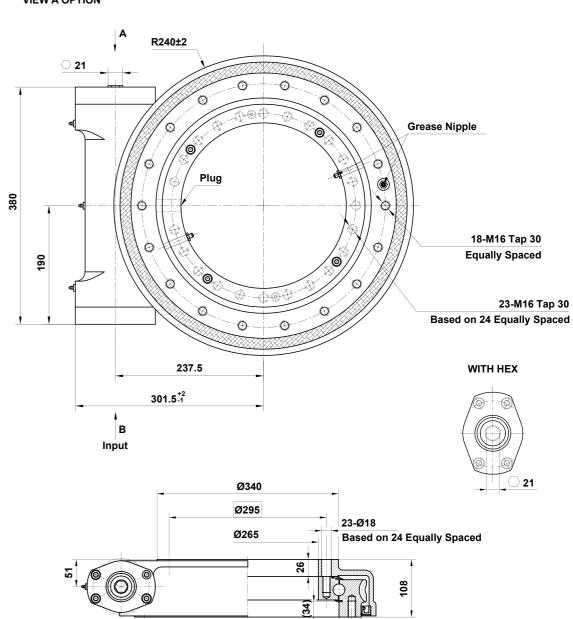


Notice: Please be sure to remain under this curve.





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Ø342

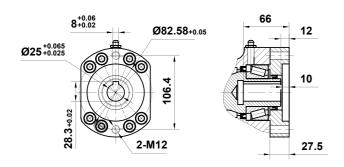
Ø390

Ø426

UNITS: mm

1 inch = 25.4 mm

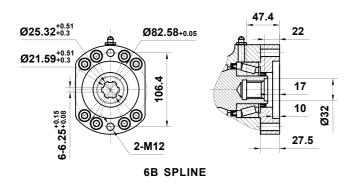




Ø12 Ø14 Ø16 Ø20 <u>Ø25</u>

□ NORMAL

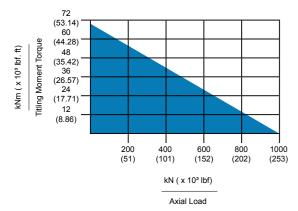
UNITS: mm 1 inch = 25.4 mm



WEA14 - Worm Drive Performance Parameters

Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
10.8 kN.m	71.2 kN.m	48 kN.m	960 kN	360 kN	230 kN	200 kN	62:1	≤ 0.150	53kg
7970 lbf.ft	52.6 x 10 ³ lbf.ft	35 x 10 ³ lbf.ft	215.8 x 10 ³ lbf	80.9 x 10 ³ lbf	51.7 x 10 ³ lbf	44.9 x 10 ³ lbf			

WEA14 - Moment Load Chart

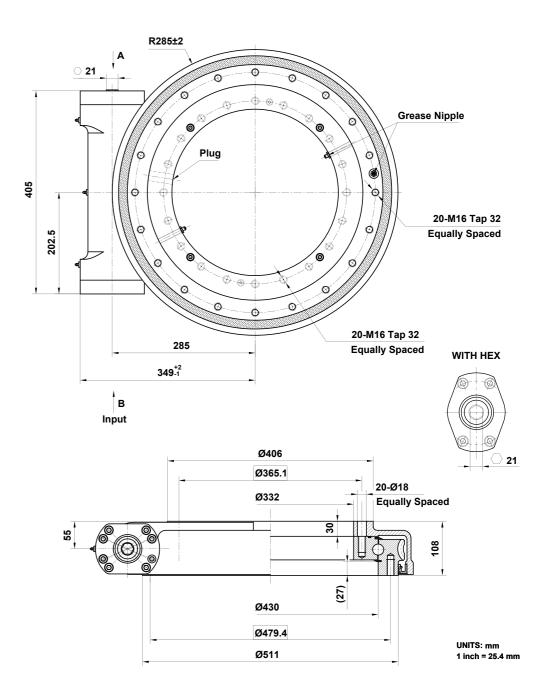


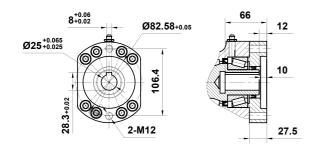
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Notice: Please be sure to remain under this curve.



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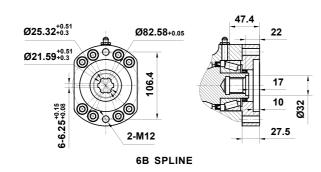




Ø12 Ø14 Ø16 Ø20 <u>Ø25</u>

□NORMAL

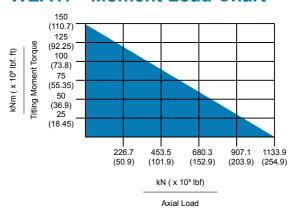
UNITS: mm 1 inch = 25.4 mm



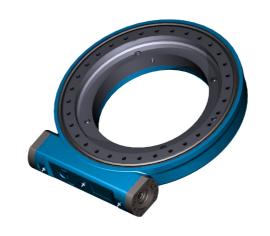
WEA17 - Worm Drive Performance Parameters

Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
12.96 kN.m	142.4 kN.m	72.3 kN.m	1166 kN	435 kN	280 kN	231 kN	104:1	≤ 0.10	96kg
9564 lbf.ft	105 x 10 ³ lbf.ft	53.4 x 10 ³ lbf.ft	262 x 10 ³ lbf	97.8 x 10 ³ lbf	62.9 x 10 ³ lbf	51.9 x 10 ³ lbf	104.1		

WEA17 - Moment Load Chart

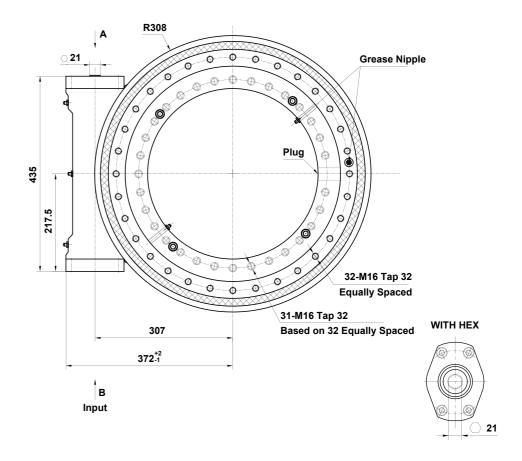


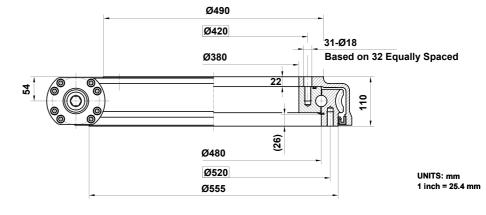
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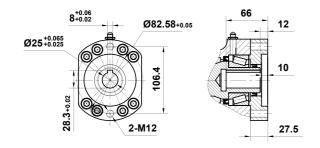


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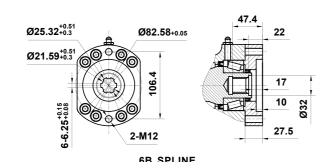




Ø12 Ø14 Ø16 Ø20 <u>Ø25</u>

□NORMAL

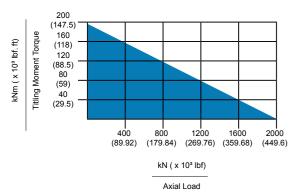
UNITS: mm 1 inch = 25.4 mm



WEA19 - Worm Drive Performance Parameters

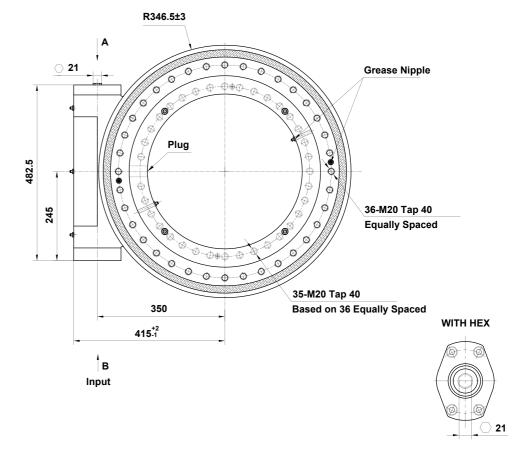
Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
18.5 kN.m	196 kN.m	86.7 kN.m	1800 kN	675 kN	290 kN	250 kN	93:1	≤ 0.10	130kg
13653 lbf.ft	144.6 x 10 ³ lbf.ft	64 x 10 ³ lbf.ft	404.6 x 10 ³ lbf	151.7 x 10 ³ lbf	65.2 x 10 ³ lbf	56.2 x 10 ³ lbf	93.1	≥ 0.10	Toukg

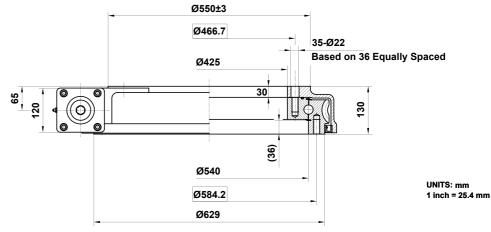
WEA19 - Moment Load Chart



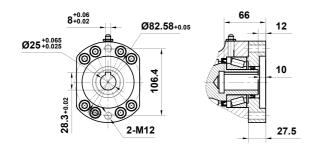
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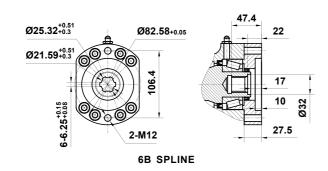




Ø12 Ø14 Ø16 Ø20 <u>Ø25</u>

□NORMAL

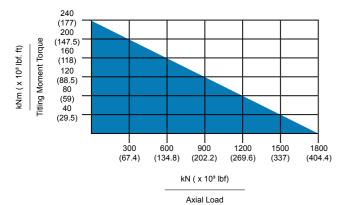
UNITS: mm 1 inch = 25.4 mm



WEA21 - Worm Drive Performance Parameters

Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
28.7 kN.m	203 kN.m	105.8 kN.m	1598 kN	640 kN	385 kN	335 kN	90:1	≤ 0.10	1701
21180 lbf.ft	150 x 10 ³ lbf.ft	78.1 x 10 ³ lbf.ft	359 x 10 ³ lbf	144 x 10 ³ lbf	87 x 10 ³ lbf	75 x 10 ³ lbf	90.1	≥ 0.10	172kg

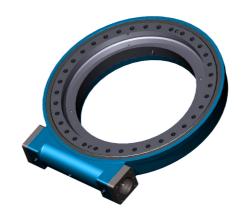
WEA21 - Moment Load Chart



Notice: Please be sure to remain under this curve.

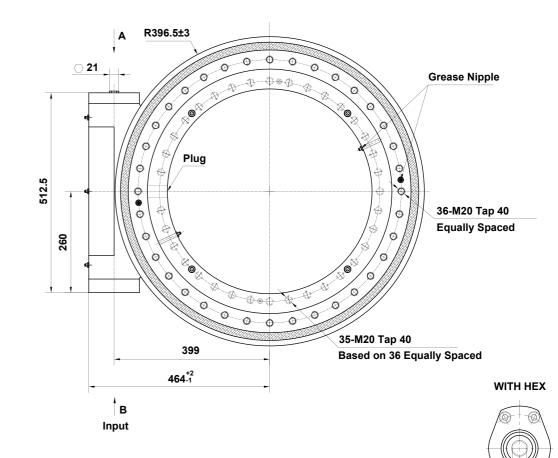
Every effort has been taken to ensure that the data listed in this catalogue is correct.

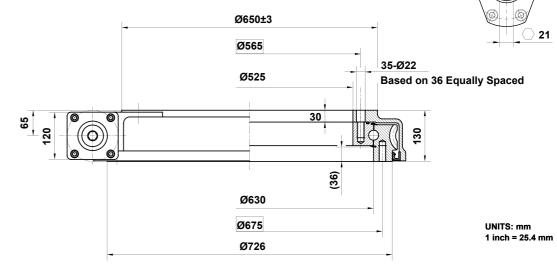
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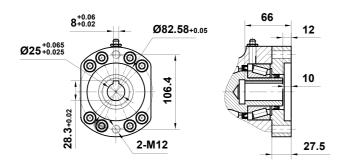


87

WEA25



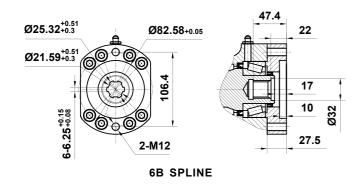
VIEW B OPTION



Ø12 Ø14 Ø16 Ø20 <u>Ø25</u>

□NORMAL

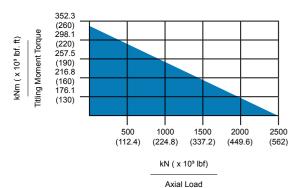
UNITS: mm 1 inch = 25.4 mm



WEA25 - Worm Drive Performance Parameters

Output Torque	Tilting Moment Torque	Holding Torque	Static Axial Rating	Static Radial Rating	Dynamic Axial Rating	Dynamic Radial Rating	Gear Ratio	Tracking Precision	Weight
34.2 kN.m	310 kN.m	158.3 kN.m	2360 kN	945 kN	590 kN	470 kN	93:1	≤ 0.10	130kg
25240 lbf.ft	229 x 10 ³ lbf.ft	117 x 10 ³ lbf.ft	531 x 10 ³ lbf	212 x 10 ³ lbf	133 x 10 ³ lbf	106 x 10 ³ lbf			

WEA25 - Moment Load Chart



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